

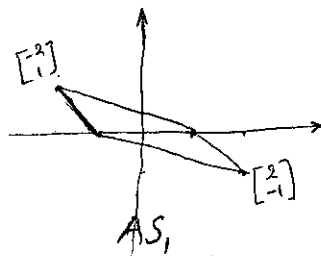
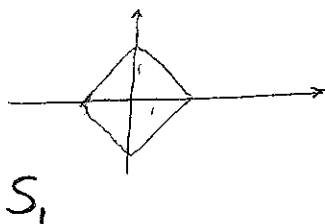
problem #1 :  $A = \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}$

a) We know that  $\|A\|_1 = \sup_{\|u\|_1=1} \|Au\|_1 = \sup_{\|u\|_1=1} \|Au\|_1$

$A \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} u_1 + 2u_2 \\ -u_2 \end{bmatrix} \Rightarrow \|Au\|_1 = |u_1 + 2u_2| + |-u_2| \leq |u_1| + 3|u_2| = 1 + 2|u_2| \leq 3$  since

We know that  $|u_1| + |u_2| = 1$  so  $|u_2| \leq 1$  so  $\|Au\|_1 \leq 3$  and for  $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$  it takes sup value

so  $u = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ ,  $Au = v = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$



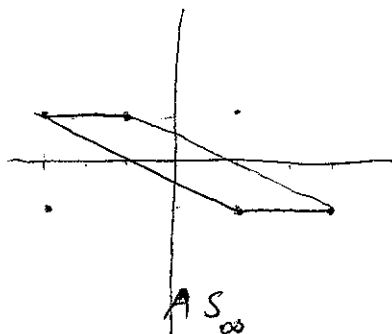
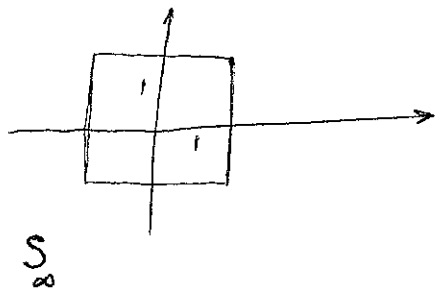
b) by definition we know that  $\|A\|_\infty$  equals 1-norm of rows of A, but A

has two rows  $[1, 2]$  and  $[0, -1]$  and their norms are 3, 1 respectively.

so  $\|A\|_\infty = 3$  and assume  $u = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$  then  $Au = \begin{bmatrix} 3 \\ -1 \end{bmatrix}$  and

$\|Au\|_\infty = \max\{|3|, |-1|\} = 3$  (note that  $\|u\|_\infty = 1$ ) so we found  $u$  such

that  $\|Au\|_\infty = \|A\|_\infty$ .



c) We try to find  $\|A\|_2$  by verifying  $Au$  where  $u = \begin{bmatrix} \cos\theta \\ \sin\theta \end{bmatrix}$  so:

$$Au = \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} \cos\theta \\ \sin\theta \end{bmatrix} = \begin{bmatrix} \cos\theta + 2\sin\theta \\ -\sin\theta \end{bmatrix} \Rightarrow \|Au\|_2^2 = \cos^2\theta + 4\sin^2\theta + 4\sin\theta\cos\theta + \sin^2\theta \\ = 1 + 4\sin\theta(\sin\theta + \cos\theta)$$

So  $\|A\|_2 = \sup_{\|u\|_2=1} \|Au\|_2$

So  $\frac{\partial (\|Au\|_2^2)}{\partial \theta} = 4\cos\theta(\sin\theta + \cos\theta) + 4\sin\theta(\cos\theta - \sin\theta) = 8\sin\theta\cos\theta + 4\cos 2\theta \\ = 4\sin 2\theta + 4\cos 2\theta$

So for max  $\frac{\partial (\|Au\|_2^2)}{\partial \theta} = 0 \Rightarrow \sin 2\theta = -\cos 2\theta \Rightarrow \tan 2\theta = -1$  so

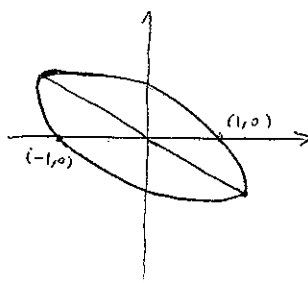
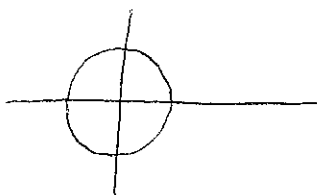
$2\theta = k\pi + \frac{3\pi}{4}$  so  $\theta = k\frac{\pi}{2} + \frac{3\pi}{8}$  takes  $k=0$  for example

We get  $\theta = \frac{3\pi}{8}$  and  $\|Au\|_2^2 = 4\sin^2\frac{3\pi}{8} + 4\sin\frac{3\pi}{8}\cos\frac{3\pi}{8} = 2(1 - \cos\frac{3\pi}{4}) + 2\sin\frac{3\pi}{4} \\ = 2(1 + \frac{\sqrt{2}}{2}) + 2\frac{\sqrt{2}}{2} = 4\sqrt{2} + 2$

(you can easily check with second derivative criteria that  $\frac{3\pi}{8}$  gives max not min)

So the max  $\|Au\|_2$  is  $\sqrt{4\sqrt{2} + 2}$  so  $\|A\|_2 = \sqrt{4\sqrt{2} + 2}$

and  $u$  that  $\|Au\|_2 = \|A\|_2$  is  $\begin{bmatrix} \cos\frac{3\pi}{8} \\ \sin\frac{3\pi}{8} \end{bmatrix}$



problem #2 : if  $P$  is projector then since  $\|P\|_2 = \sup_{\|u\|=1} \|Pu\|_2$  so

$\|P\|_2 \geq \|Pu\|_2$  ( $\|u\|_2=1$ ) so choose a unit vector in range  $P$  then  $u \in \text{range}(P)$

so  $Pu=u$  so  $\|Pu\|_2 = \|u\|_2 = 1$  so  $\|P\|_2 \geq 1$  \*

now assume that  $P$  is orthogonal projector then we know that  $\text{range}(P) \perp \text{ker}(P)$

so for any vector  $u$  we have:

$$u = \underbrace{(u-Pu)}_{\text{ker } P} + \underbrace{Pu}_{\text{range}(P)} \implies \|u\|_2^2 = \|u-Pu\|_2^2 + \|Pu\|_2^2 \geq \|Pu\|_2^2$$

so  $\frac{\|Pu\|_2}{\|u\|_2} \leq 1 \implies \|P\|_2 \leq 1$  but by \* we know  $\|P\|_2 \geq 1$  so  $\|P\|_2 = 1$

now assume  $\|P\|_2 = 1$ . in order to show  $P$  is orthogonal projector again we

have to show  $\text{range}(P) \perp \text{ker}(P)$  so assume contrary then it means

that there exists  $u$  such that  $u \perp \text{ker } P$  but  $u \notin \text{range}(P)$  so

$$P(Pu-u) = 0 \implies Pu-u \in \text{ker } P \implies u \perp Pu-u \implies Pu = \underbrace{(Pu-u)}_{\text{ker } P} + \underbrace{u}_{\text{ker } P} \perp$$

so  $\|Pu\|_2^2 = \|Pu-u\|_2^2 + \|u\|_2^2 \implies \|Pu\|_2 > \|u\|_2$  so  $\|P\|_2 > 1$  but

we know that  $\|P\|_2 = 1$ . contradiction so  $\text{range } P \perp \text{ker } P$  so

$P$  is orthogonal projector.

problem #4

assume  $u = [u_1, \dots, u_m]$  and  $v = [v_1, \dots, v_n]$

$$\|u\|_F^2 = \sum_{i=1}^m |u_i|^2$$

$$\|v\|_F^2 = \sum_{i=1}^n |v_i|^2$$

$$uv^* = \begin{bmatrix} u_1 \bar{v}_1 & u_1 \bar{v}_2 & \dots \\ u_2 \bar{v}_1 & & \\ \vdots & & \\ u_m \bar{v}_1 & & \dots & u_m \bar{v}_n \end{bmatrix}$$

$$\text{so } \|uv^*\|_F^2 = \sum_{ij} |u_i \bar{v}_j|^2$$

but  $|u_i \bar{v}_j| = |u_i| |\bar{v}_j| = |u_i| |v_j|$  so

$$\|u\|_F^2 \|v\|_F^2 = \left( \sum_{i=1}^m |u_i|^2 \right) \left( \sum_{j=1}^n |v_j|^2 \right) = \sum_{ij} |u_i|^2 |v_j|^2 = \sum_{ij} |u_i \bar{v}_j|^2 = \|uv^*\|_F^2$$

$$\text{so } \|u\|_F \|v\|_F = \|uv^*\|_F$$