

1. Definition $f: \mathbb{R}^m \rightarrow \mathbb{R}^n$, $f = (f_1, \dots, f_n)$ is differentiable at $a \in \mathbb{R}^m$ iff the following two conditions are satisfied:

$$\alpha) \quad \frac{\partial f_i}{\partial x_j}(a) \text{ exist,} \quad \begin{array}{l} 1 \leq i \leq n \\ 1 \leq j \leq m \end{array}$$

$$\beta) \quad \lim_{x \rightarrow a} \frac{f(x) - f(a) - [Df(a)](x-a)}{\|x-a\|} = 0,$$

where $[Df(a)]: \mathbb{R}^m \rightarrow \mathbb{R}^n$ is the linear map determined by the matrix of partial derivatives computed at a:

$$Df(a) = \begin{pmatrix} \frac{\partial f_1}{\partial x_1}(a) & \dots & \frac{\partial f_1}{\partial x_m}(a) \\ \vdots & & \vdots \\ \frac{\partial f_n}{\partial x_1}(a) & \dots & \frac{\partial f_n}{\partial x_m}(a) \end{pmatrix}$$

Notation $f'(a) = [Df(a)]$

so $\begin{cases} f'(a): \mathbb{R}^m \rightarrow \mathbb{R}^n \text{ is a linear map} \\ Df(a) = \text{"just" a matrix } (n \times m) \end{cases}$

Example If $F: \mathbb{R}^m \rightarrow \mathbb{R}^n$ is linear, i.e.

$F(x) = B \cdot x$, where $B = (n \times m)$ -matrix, then

$$F'(a) = F, \quad \forall a \in \mathbb{R}^m$$

2. If $f: \mathbb{R}^3 \rightarrow \mathbb{R}$ is differentiable at $a = (x_0, y_0, z_0) \in \mathbb{R}^3$,

then $Df(a) = \left(\frac{\partial f}{\partial x}(a), \frac{\partial f}{\partial y}(a), \frac{\partial f}{\partial z}(a) \right)$, hence

the linear map $f'(a): \mathbb{R}^3 \rightarrow \mathbb{R}$ is given by

$$f'(a)(\vec{v}) = \nabla f(a) \cdot \vec{v}$$

3. THEOREM $[C^1 \Rightarrow \text{DIFF}]$ $f = (f_1, \dots, f_n): \mathbb{R}^m \rightarrow \mathbb{R}^n$

If $\frac{\partial f_i}{\partial x_j}$ exist ~~and~~ ($1 \leq i \leq n, 1 \leq j \leq m$)

AND are continuous at a (everywhere),

THEN f is differentiable at a (everywhere).

4. Example $f: \mathbb{R}^2 \rightarrow \mathbb{R}$, $f(x, y) = x \sin y$.

Then $\frac{\partial f}{\partial x}(x, y) = \sin y$, $\frac{\partial f}{\partial y}(x, y) = x \cos y$, hence

$\frac{\partial f}{\partial x}$, $\frac{\partial f}{\partial y}: \mathbb{R}^2 \rightarrow \mathbb{R}$ are continuous everywhere, so f is differentiable everywhere.

Note $Df(x, y) = (\sin y, x \cos y)$

$f'(x, y): \mathbb{R}^2 \rightarrow \mathbb{R}$, $f'(x, y)(\vec{v}) = \nabla f(x, y) \cdot \vec{v}$.

Example. For $(x, y) = (1, 0)$,

$f'(1, 0): \mathbb{R}^2 \rightarrow \mathbb{R}$, $f'(1, 0)(\vec{v}) = \vec{j} \cdot \vec{v}$

4. Directional Derivatives

a. Definition For $\vec{v} \neq 0$ and $f: \mathbb{R}^m \rightarrow \mathbb{R}^n$, $a \in \mathbb{R}^m$,

$$\partial_{\vec{v}} f(a) = \lim_{t \rightarrow 0} \frac{f(a+t\vec{v}) - f(a)}{t}$$

(rate of change along \vec{v}).

b) THEOREM If $f: \mathbb{R}^m \rightarrow \mathbb{R}^n$ is differentiable at a ,

then for every $\vec{v} \neq 0$, $\boxed{\partial_{\vec{v}} f(a) = f'(a)(\vec{v})}$

c) Particular case.

Say $f: \mathbb{R}^3 \rightarrow \mathbb{R}$ is differentiable at $a \in \mathbb{R}^3$.

Then, for $\vec{v} \neq 0$,

$$\boxed{\partial_{\vec{v}} f(a) = \nabla f(a) \cdot \vec{v}}$$

5. Direction of greatest increase.

Let \vec{v} a unit vector in \mathbb{R}^3 , $\|\vec{v}\| = 1$, and $f: \mathbb{R}^3 \rightarrow \mathbb{R}$ differentiable at $a \in \mathbb{R}^3$. We can write

$$\begin{aligned} \partial_{\vec{v}} f(a) &= \nabla f(a) \cdot \vec{v} = \|\nabla f(a)\| \cdot \|\vec{v}\| \cdot \cos \theta \\ &= \|\nabla f(a)\| \cdot \cos \theta \end{aligned}$$

where $\theta = \angle(\nabla f(a), \vec{v})$

Therefore $\partial_{\vec{v}} f(a)$ is maximal \neq when $\theta = 0$, in other words for the direction

$$\vec{V}_{\max} = \frac{\nabla f(a)}{\|\nabla f(a)\|}$$

(the unit vector along $\nabla f(a)$).

The actual value of this greatest rate of change is

$$\begin{aligned} \nabla f(a) \cdot \vec{v}_{\max} &= \|\nabla f(a)\| \\ &= \sqrt{\left(\frac{\partial f}{\partial x}(a)\right)^2 + \left(\frac{\partial f}{\partial y}(a)\right)^2 + \left(\frac{\partial f}{\partial z}(a)\right)^2} \end{aligned}$$

6. Chain Rule

Theorem

$$\begin{array}{ccccc} \mathbb{R}^m & \xrightarrow{f} & \mathbb{R}^n & \xrightarrow{g} & \mathbb{R}^k \\ \downarrow & & \downarrow & & \downarrow \\ a & \longmapsto & f(a) & \longmapsto & g(f(a)) \end{array}$$

Assume $f: \mathbb{R}^m \rightarrow \mathbb{R}^n$ is differentiable at $\underline{a} \in \mathbb{R}^m$.

— " — $g: \mathbb{R}^n \rightarrow \mathbb{R}^k$ — " — $f(a) \in \mathbb{R}^n$.

THEN $f \circ g: \mathbb{R}^m \rightarrow \mathbb{R}^k$ is differentiable at a ,

and

$$\boxed{(f \circ g)'(a) = g'(f(a)) \circ f'(a)}$$

composition of linear maps

$$\mathbb{R}^m \xrightarrow{f'(a)} \mathbb{R}^n \xrightarrow{g'(f(a))} \mathbb{R}^k$$

In terms of matrices,

matrix multiplication

$$D_{f \circ g}(a) = D_g(f(a)) \cdot D_f(a)$$

Example

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$f(x,y) = (x^2+y, x+y)$$

$$g: \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$g(x,y) = xy$$

$$\mathbb{R}^2 \xrightarrow{f} \mathbb{R}^2 \xrightarrow{g} \mathbb{R}$$

$$g \circ f: \mathbb{R}^2 \rightarrow \mathbb{R}$$

a) Compute $D_f(x,y) = \begin{pmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial y} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} \end{pmatrix} = \begin{pmatrix} 2x & 1 \\ 1 & 1 \end{pmatrix}$.

b) Compute $D_g(x,y) = \left(\frac{\partial g}{\partial x}, \frac{\partial g}{\partial y} \right) = (y, x)$

Hence $D_g(f(x,y)) = D_g(x^2+y, x+y) = (x+y, x^2+y)$.

d) Compute $D_{g \circ f}(x,y)$.

First, $g \circ f(x,y) = g(f(x,y)) = g(x^2+y, x+y) = (x^2+y)(x+y)$
 $= x^3 + x^2y + xy + y^2$

Hence $D_{g \circ f}(x,y) = (3x^2 + 2xy + y, x^2 + x + 2y)$

e) Verify that $D_g(f(x,y)) \cdot D_f(x,y) = D_{g \circ f}(x,y)$:

$$(x+y, x^2+y) \begin{pmatrix} 2x & 1 \\ 1 & 1 \end{pmatrix} = (3x^2 + 2xy + y, x^2 + x + 2y)$$

7. Important application

Assume $\gamma(t) = (x(t), y(t), z(t)) : \mathbb{R} \rightarrow \mathbb{R}^3$ is a differentiable path. (this amounts to $x(t), y(t), z(t)$ differentiable as functions of t).

Let $f: \mathbb{R}^3 \rightarrow \mathbb{R}$ a differentiable map.

$$\mathbb{R} \xrightarrow{\gamma} \mathbb{R}^3 \xrightarrow{f} \mathbb{R}$$

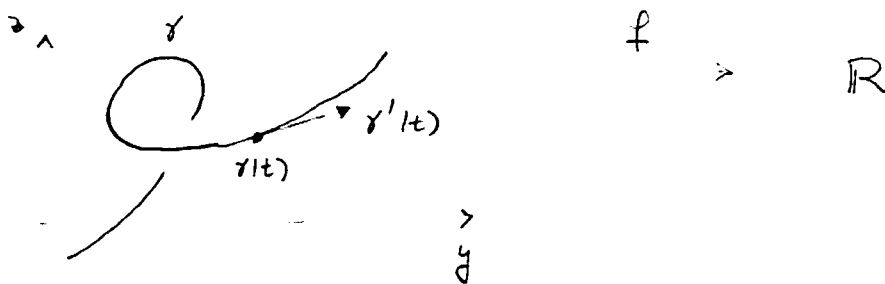
$\underbrace{\hspace{10em}}_{\varphi}$

Let $\varphi = f \circ \gamma$, $\varphi(t) = f(\gamma(t))$, then $\varphi: \mathbb{R} \rightarrow \mathbb{R}$

Chain Rule implies:

$$\varphi'(t) = D_{\varphi}(\gamma(t)) \cdot D_{\gamma}(t)$$

$$\boxed{\varphi'(t) = \nabla f(\gamma(t)) \cdot \gamma'(t)}$$



Example $\gamma(t) = (\sin t, \cos t, t)$, $f(x, y, z) = xyz$.

For $\varphi(t) = f(\gamma(t)) = \sin t \cdot \cos t \cdot t$, we have:

$$\varphi'(t) = \nabla f(\gamma(t)) \cdot \gamma'(t) \quad \text{But } \nabla f(x, y, z) = (yz, xz, xy),$$

$$\Rightarrow \nabla f(\gamma(t)) = (t \cos t, t \sin t, \sin t \cos t)$$

$$\text{Also } \gamma'(t) = (\cos t, -\sin t, 1).$$

$$\varphi'(t) = t \cos^2 t - t \sin^2 t + \sin t \cos t.$$

8. Geometric Interpretation

$f: \mathbb{R}^3 \rightarrow \mathbb{R}$ differentiable

Level sets: $L_c = \{ (x, y, z) \in \mathbb{R}^3 \mid f(x, y, z) = c \}$

Note Given $c \in \mathbb{R}$, $L_c =$ surface in \mathbb{R}^3 .

Theorem

For $a \in L_c$, $\nabla f(a) \perp \underbrace{T_a(L_c)}$

$\wedge \nabla f(a)$ tangent plane to L_c at a .

$T_a(L_c)$



L_c

Note $T_a(L_c) =$ spanned by the vectors $\gamma'(0)$, where $\gamma(t)$ is a curve inside L_c , such that $\gamma(0) = a$.

In other words, to prove the theorem we need to prove the following:

Given $\gamma(t) \in L_c$, $\gamma(0) = a$.

Then $\nabla f(a) \perp \gamma'(0)$

Put $\varphi(t) = f(\gamma(t))$.

Since $\gamma(t) \in L_c, \forall t \Rightarrow \varphi(t) = c, \forall t$.

Hence $\varphi'(0) = 0$.

But $\varphi'(0) = \nabla f(\gamma(0)) \cdot \gamma'(0) = \nabla f(a) \cdot \gamma'(0) \Rightarrow \nabla f(a) \cdot \gamma'(0) = 0$

9. Equation of the tangent plane. $\rightarrow a = (x_0, y_0, z_0)$

Let $f: \mathbb{R}^3 \rightarrow \mathbb{R}$ differentiable, $a \in \mathbb{R}^3$, and set

$c = f(a)$. Then $a \in L_c$ (surface).

The plane $T_a(L_c)$ passes through a and $\perp \nabla f(a)$.

Equation of $T_a(L_c)$:

$$\frac{\partial f}{\partial x}(a)(x-x_0) + \frac{\partial f}{\partial y}(a)(y-y_0) + \frac{\partial f}{\partial z}(a)(z-z_0) = 0$$

10. Tangent plane to the graph of $f: \mathbb{R}^2 \rightarrow \mathbb{R}$

The graph of f is the set $\{(x, y, f(x, y)) \mid (x, y) \in \mathbb{R}^2\}$.

It can be seen as the level set L_0 of the function $F: \mathbb{R}^3 \rightarrow \mathbb{R}$,

$$F(x, y, z) = f(x, y) - z$$

Therefore the tangent plane @ (x_0, y_0) is

$$\frac{\partial F}{\partial x}(x_0, y_0, z_0)(x-x_0) + \frac{\partial F}{\partial y}(x_0, y_0, z_0)(y-y_0) + \frac{\partial F}{\partial z}(x_0, y_0, z_0)(z-z_0) = 0$$

$$\Leftrightarrow \frac{\partial f}{\partial x}(x_0, y_0)(x-x_0) + \frac{\partial f}{\partial y}(x_0, y_0)(y-y_0) - (z - f(x_0, y_0)) = 0$$

$$\Leftrightarrow \boxed{z = f(x_0, y_0) + \frac{\partial f}{\partial x}(x_0, y_0)(x-x_0) + \frac{\partial f}{\partial y}(x_0, y_0)(y-y_0)}$$