

problem #1

a) We try to find QR factorization of A by Gram-Schmidt

Orthogonalization.

$$A = \begin{bmatrix} 3 & 1 \\ -4 & 0 \\ 0 & -1 \end{bmatrix} \begin{array}{c} a_1 \\ a_2 \end{array}$$

normalize a_1, a_2 :

$$c_1 := \frac{1}{5} \begin{bmatrix} 3 \\ -4 \\ 0 \end{bmatrix} \quad c_2 := \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$$

$$q_1 = c_1 \quad q_2 = \frac{c_2 - \langle c_1, c_2 \rangle c_1}{\|c_2 - \langle c_1, c_2 \rangle c_1\|}$$

$$q_1 = \frac{1}{5} \begin{bmatrix} 3 \\ -4 \\ 0 \end{bmatrix}$$

$$q_2 = \frac{5}{\sqrt{41}} \begin{bmatrix} \frac{16}{25} \\ \frac{12}{25} \\ -1 \end{bmatrix}$$

$$a_1 = 5q_1, \quad a_2 = \frac{\sqrt{41}}{5}q_2 + \frac{3}{5}q_1$$

$$\text{So } A = \begin{bmatrix} \frac{3}{5} & \frac{16}{5\sqrt{41}} \\ -\frac{4}{5} & \frac{12}{5\sqrt{41}} \\ 0 & -\frac{5}{\sqrt{41}} \end{bmatrix} \begin{bmatrix} 5 & \frac{\sqrt{41}}{5} \\ 0 & \frac{3}{5} \end{bmatrix}$$

Q R

(b) from Thm 11.1 We have to solve:

$$A^*Ax = A^*b \quad \text{which is}$$

for $b_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

$$\begin{bmatrix} 3 & -4 & 0 \\ 1 & 0 & -1 \end{bmatrix} \begin{bmatrix} 3 & 1 \\ -4 & 0 \\ 0 & -1 \end{bmatrix} x_1 = \begin{bmatrix} 3 & -4 & 0 \\ 1 & 0 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 25 & 3 \\ 3 & 2 \end{bmatrix} x_1 = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$$

$$x_1 = \frac{1}{41} \begin{bmatrix} 2 & -3 \\ -3 & 25 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \frac{1}{41} \begin{bmatrix} 3 \\ 16 \end{bmatrix}$$

for $b_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$

$$\begin{bmatrix} 25 & 3 \\ 3 & 2 \end{bmatrix} x_2 = \begin{bmatrix} 3 & -4 & 0 \\ 1 & 0 & -1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -4 \\ 0 \end{bmatrix}$$

$$x_2 = \frac{1}{41} \begin{bmatrix} 2 & -3 \\ -3 & 25 \end{bmatrix} \begin{bmatrix} -4 \\ 0 \end{bmatrix} = \frac{1}{41} \begin{bmatrix} -8 \\ 12 \end{bmatrix}$$

now

$$\|Ax_1 - b_1\|_2 = \left\| \frac{1}{41} \begin{bmatrix} -16 \\ -12 \\ -16 \end{bmatrix} \right\|_2$$

$$\|Ax_2 - b_2\|_2 = \left\| \frac{1}{41} \begin{bmatrix} -12 \\ -9 \\ -12 \end{bmatrix} \right\|_2$$

since $\left\| \begin{bmatrix} -16 \\ -12 \\ -16 \end{bmatrix} \right\|_2 > \left\| \begin{bmatrix} -12 \\ -9 \\ -12 \end{bmatrix} \right\|_2$

so $\|Ax_1 - b_1\|_2 > \|Ax_2 - b_2\|_2$

so x_2 is nearer to true

solution.

problem #2: We want to find line $y = ax + b$ that is best solution in a sense that those three points lie on this line

So: $y = a_1 x + b_1$

$$\begin{aligned} 1 &= 2a_1 + b_1 \\ -1 &= 0a_1 + b_1 \\ 2 &= 5a_1 + b_1 \end{aligned} \implies \begin{bmatrix} 2 & 1 \\ 0 & 1 \\ 5 & 1 \end{bmatrix} \begin{bmatrix} a_1 \\ b_1 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}$$
$$A \vec{x} = \vec{b}$$

So like problem #1 in order to find best solution to $A\vec{x} = \vec{b}$ we have to minimize the error $r = b - Ax$ and by Thm 11.1 we know best solution satisfies: $A^* A x = A^* b$

$$\begin{bmatrix} 2 & 0 & 5 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 0 & 1 \\ 5 & 1 \end{bmatrix} x = \begin{bmatrix} 2 & 0 & 5 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} = \begin{bmatrix} 12 \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} 29 & 7 \\ 7 & 3 \end{bmatrix} \begin{bmatrix} a_1 \\ b_1 \end{bmatrix} = \begin{bmatrix} 12 \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} a_1 \\ b_1 \end{bmatrix} = \frac{1}{38} \begin{bmatrix} 3 & -7 \\ -7 & 29 \end{bmatrix} \begin{bmatrix} 12 \\ 2 \end{bmatrix} = \frac{1}{38} \begin{bmatrix} 22 \\ -26 \end{bmatrix}$$

~~Problem #2~~ So our Goal is to find best solution to

~~(assume your line is $y = ax + b$)~~

~~$a + b = 2$~~

~~$a(0) -$~~

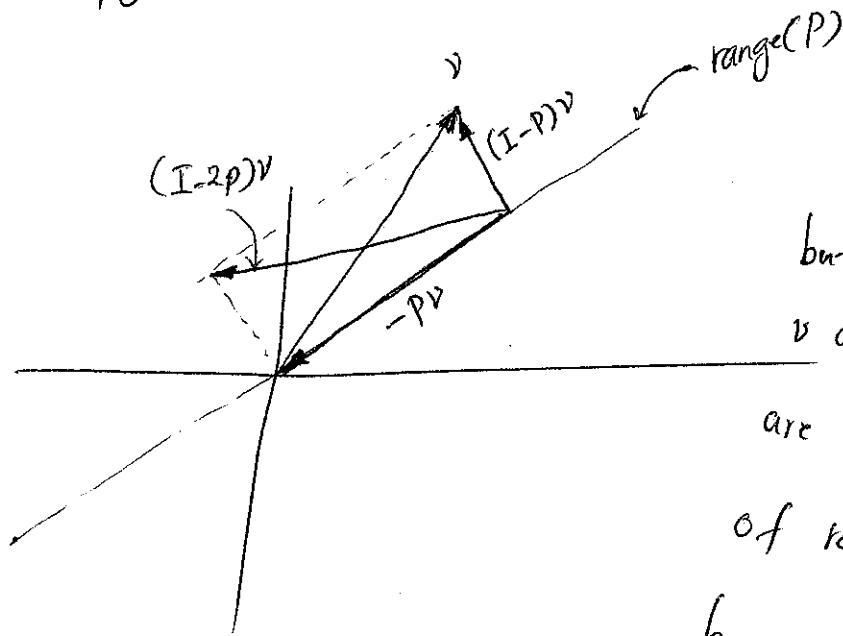
Problem #3: by Thm 6.1 we know $P = P^*$ so

$$\begin{aligned}(I - 2P)(I - 2P)^* &= (I - 2P)(I - 2P) \\ &= I - 4P + \underbrace{4P^2}_{P^2=P} = I\end{aligned}$$

so $I - 2P$ is unitary matrix.

Actually geometric interpretation is $I - 2P$ preserves the norm

like the figure below:



but as you see
 v and $(I - 2P)v$
are two diagonals
of rectangle so they
have equal length.

problem #4: assume $A = [a_1 | a_2 | \dots | a_n]$

then like (7.3) we have

$$a_1 = r_{11} q_1$$

$$a_2 = r_{12} q_1 + r_{22} q_2$$

$$a_3 = r_{13} q_1 + r_{23} q_2 + r_{33} q_3$$

$$\text{Claim } \hat{R} = \begin{bmatrix} r_{11} & 0 & r_{13} & 0 & r_{15} \\ & r_{22} & 0 & r_{24} & 0 \\ & & r_{33} & 0 & r_{35} \\ & & & r_{44} & 0 \\ & & & & r_{55} \\ & & & & \dots \end{bmatrix}$$

Since we have assumed $m \geq n$ and A has rank n so a_i are independent.

ident. and $\langle a_{2k}, a_{2k+1} \rangle = 0$ so $\langle a_1, a_2 \rangle = 0 \implies r_{11} r_{12} = 0 \implies r_{12} = 0$

$\langle a_2, a_3 \rangle = 0 \implies r_{22} r_{23} = 0 \implies r_{23} = 0$, $\langle a_1, a_4 \rangle = 0 \implies r_{11} r_{14} = 0 \implies r_{14} = 0$

$\langle a_3, a_4 \rangle = 0 \implies r_{33} r_{34} = 0 \implies r_{34} = 0$ (since a_1, a_3 are independent so $r_{33} \neq 0$)

So we prove by induction $a_{2k} = r_{22k} q_2 + r_{42k} q_4 + \dots$

$$a_{2k+1} = r_{12k+1} q_1 + r_{32k+1} q_3 + \dots$$

Assume we proved for $i < k$ we want to prove a_{2k}

$\langle a_1, a_{2k} \rangle = 0 \implies r_{11} r_{12k} = 0 \implies r_{12k} = 0$ now again by induction

assume $r_{2l+1, 2k} = 0$ for $l < j$ then $\langle a_{2j+1}, a_{2k} \rangle = 0 \implies r_{2j+1, 2j+1} r_{2j+1, 2k} = 0$

$\implies r_{2j+1, 2k} = 0$ so by induction all $r_{2l+1, 2k} = 0$ and similarly all $r_{2k, 2l+1} = 0$

so we proved the claim.

Problem #5

(a) $\|x\|_\infty \stackrel{?}{\leq} \|x\|_2$ $x = (x_1, \dots, x_m)$

assume $\max |x_i| = |x_1|$ then

$$\|x\|_2^2 = \sum_{i=1}^m x_i^2 \geq x_1^2 = |x_1|^2 = \|x\|_\infty^2 \Rightarrow \|x\|_2 \geq \|x\|_\infty$$

and for example for $(1, 0, \dots, 0)$ equality holds.

(b) $\|x\|_2 \stackrel{?}{\leq} \sqrt{m} \|x\|_\infty$

again assume $\|x\|_\infty = |x_1|$ then

$$\|x\|_2^2 = x_1^2 + \dots + x_m^2 \leq x_1^2 + x_1^2 + \dots + x_1^2 = m x_1^2 = (\sqrt{m} \|x\|_\infty)^2 \Rightarrow \|x\|_2 \leq \sqrt{m} \|x\|_\infty$$

and for example for $(1, 1, \dots, 1)$ equality holds.

(c) $\|A\|_\infty \stackrel{?}{\leq} \sqrt{n} \|A\|_2$

$\|A\|_2 = \sup \frac{\|Ax\|_2}{\|x\|_2}$ so if we find x such that $\sqrt{n} \frac{\|Ax\|_2}{\|x\|_2} \geq \|A\|_\infty$

then we are done take $x = (\pm 1, \dots, \pm 1)$ then $\|x\|_2 = \sqrt{n}$

and $Ax = \begin{bmatrix} r_1 \\ r_2 \\ \vdots \\ r_m \end{bmatrix} \begin{bmatrix} \pm 1 \\ \vdots \\ \pm 1 \end{bmatrix} = \begin{bmatrix} \|r_1\|_1 \\ * \\ \vdots \\ * \end{bmatrix}$, assume $\|A\|_\infty = \|r_1\|_1$ and

choose \pm in each coordinate of x such $\langle r_1, x \rangle = \|r_1\|_1$

so first coordinate of Ax is $\|r_1\|_1$ so $\|Ax\|_2 \geq \|r_1\|_1 = \|A\|_\infty$

so we are done.

$$\geq (\sum r_i^j x_j)^2 + \dots + (\sum r_m^j x_j)^2$$

$$\geq \sum_i (\sum_j r_i^j x_j)^2 = \|Ax\|_2^2$$

$$\implies m \|A\|_\infty^2 \|x\|_2^2 \geq \|Ax\|_2^2$$

so $\forall x$ $\frac{\|Ax\|_2^2}{\|x\|_2^2} \leq m \|A\|_\infty^2 \implies \|A\|_2 \leq \sqrt{m} \|A\|_\infty$

and trivially for example equality holds for $\begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & & \\ \vdots & & \ddots & \\ 0 & & & 1 \end{bmatrix}$

Sketch of Bonus Problem

$$(a) F = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} \sin \theta & \cos \theta \\ -\cos \theta & \sin \theta \end{bmatrix} = \left[\text{reflection by line } y=x \right] \circ R_{\theta - \pi/2}$$

$R_{\theta - \pi/2}$ is rotation over origin by $\theta - \pi/2$

$$J = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} = R_{-\theta} \quad \text{so is rotation by } \theta \text{ clockwise.}$$

(b) like the figure 10.1 in each step we have to find

$$\text{an operator } F \text{ such that } x = \begin{bmatrix} x \\ \vdots \\ x \end{bmatrix} \longrightarrow Fx = \begin{bmatrix} \|x\| \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

but obviously we can do it with sequence of two dimensional rotations

$$x = \begin{bmatrix} x_1 \\ \vdots \\ x_l \end{bmatrix}, \text{ first apply appropriate } J \text{ s.t. } J \begin{bmatrix} x_{l-1} \\ x_l \end{bmatrix} = \begin{bmatrix} \|v_1\| \\ 0 \end{bmatrix}$$

$$\text{and then apply appropriate } J \text{ such that } J \begin{bmatrix} x_{l-2} \\ \|v_1\| \end{bmatrix} = \begin{bmatrix} \|v_2\| \\ 0 \end{bmatrix}$$

$$\text{and repeat until you get } \begin{bmatrix} \|x\| \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

$$(c) \text{ each } J \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} \cos \theta a + \sin \theta b \\ -\sin \theta a + \cos \theta b \end{bmatrix} \text{ has 6 flops since each}$$

coordinate has 2 multiplication and an addition so to get $\begin{bmatrix} \|x\| \\ 0 \\ \vdots \\ 0 \end{bmatrix}$

We need $6(l-1)$ but like 10.8 each column need $4l-1$ so we need approximately 50% more flops.