

Rules for differentiation?

- They always look like Calculus I rules..., when they make sense!
- Since the derivative of a func in Calc III is a matrix (of functions) (of numbers at a point), making new functions via algebra or composition must be compatible.

(I) Constant Multiple Rule is always the same:

For  $\vec{F}: \mathbb{X} \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$ ,  $c \in \mathbb{R}$ , if  $\vec{F}$  is diff, then  $(c\vec{F}): \mathbb{X} \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$ , is diff, and  $D(c\vec{F})(\vec{x}) = c D\vec{F}(\vec{x})$ .

(II) Sum and Diff rule only requires domains & codomains to be the same:

For  $\vec{F}, \vec{g}: \mathbb{X} \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$ ,  $\vec{h} = \vec{F} + \vec{g}$ .

$$D\vec{h}(\vec{x}) = D(\vec{F} + \vec{g})(\vec{x}) = D\vec{F}(\vec{x}) + D\vec{g}(\vec{x})$$

(III) Products are trickier, since codomains may be multidimensional:

Let  $\vec{F}: \mathbb{X} \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$ ,  $\vec{g}: \mathbb{X} \subset \mathbb{R}^n \rightarrow \mathbb{R}^p$ , and

$$\text{Let } \vec{h} = \vec{F} \circ \vec{g}.$$

III cont'd.

Here, the "dot" in  $\vec{h} = \vec{F}(\vec{x}) \cdot \vec{g}(\vec{x})$  needs to make sense. When it does, then the Product Rule from Calc I still holds:

$$D\vec{h}(\vec{x}) = D(\vec{F} \cdot \vec{g})(\vec{x}) = D\vec{F}(\vec{x}) \cdot \vec{g}(\vec{x}) + \vec{F}(\vec{x}) \cdot D\vec{g}(\vec{x})$$

ex.  $p=1$ : Here  $g(\vec{x})$  is a scalar, and  $Dg(\vec{x})$  is a  $1 \times n$  matrix, so

$$\underbrace{D\vec{h}(\vec{x})}_{m \times n} = \underbrace{D\vec{F}(\vec{x})}_{m \times n} \cdot \underbrace{g(\vec{x})}_{\text{scalar}} + \underbrace{\vec{F}(\vec{x})}_{m \times 1} \cdot \underbrace{Dg(\vec{x})}_{1 \times n} \quad \checkmark$$

examples:  $\vec{F}(x, y, z) = \begin{bmatrix} xy + y^2z \\ x^4z \end{bmatrix}$ ,  $g(x, y, z) = \ln(yz)$

$$\vec{h}(x, y, z) = \vec{F}(x, y, z) \cdot g(x, y, z) = \begin{bmatrix} (xy + y^2z) \ln(yz) \\ (x^4z) \ln(yz) \end{bmatrix}$$

$$D\vec{F}(\vec{x}) = \begin{bmatrix} y & x + 2yz & y^2 \\ 4x^3z & 0 & x^4 \end{bmatrix} \quad Dg(\vec{x}) = \left[ 0 \quad \frac{1}{y} \quad \frac{1}{z} \right]$$

Now put it all together and show equality.

$$D\vec{F}(\vec{x}) \cdot \vec{g}(\vec{x}) + \vec{F}(\vec{x}) \cdot Dg(\vec{x}) =$$

$$\begin{bmatrix} y & x + 2yz & y^2 \\ 4x^3z & 0 & x^4 \end{bmatrix} \ln(yz) + \begin{bmatrix} xy + y^2z \\ x^4z \end{bmatrix} \left[ 0 \quad \frac{1}{y} \quad \frac{1}{z} \right]$$

$$= \begin{bmatrix} y \ln(yz) & (x + 2yz) \ln(yz) & y^2 \ln(yz) \\ 4x^3z \ln(yz) & 0 & x^4 \ln(yz) \end{bmatrix} + \begin{bmatrix} \dots \\ \dots \\ \dots \end{bmatrix}$$

ex. dot product ( $m=p \geq 1$ ): if  $h(\bar{x}) = \bar{f}(\bar{x}) \cdot \bar{g}(\bar{x})$

Then  $h: \bar{X} \subset \mathbb{R}^n \rightarrow \mathbb{R}$ , and dot product,

$$Dh(\bar{x}) = [D_{x_1} h(\bar{x}) \quad \dots \quad D_{x_n} h(\bar{x})], \text{ with}$$

$$D_{x_i} h = \frac{\partial}{\partial x_i} h(\bar{x}) = \frac{\partial}{\partial x_i} \sum_{j=1}^m f_j(\bar{x}) g_j(\bar{x})$$

Sum Rule

$$= \sum_{j=1}^m \frac{\partial}{\partial x_i} (f_j(\bar{x}) g_j(\bar{x})) \quad \text{Sum Rule}$$

Calc I Product Rule

$$= \sum_{j=1}^m \frac{\partial f_j}{\partial x_i}(\bar{x}) g_j(\bar{x}) + f_j(\bar{x}) \frac{\partial g_j}{\partial x_i}(\bar{x})$$

Sum Rule

$$= \sum_{j=1}^m \underbrace{\frac{\partial f_j}{\partial x_i}(\bar{x})}_{\substack{\text{ith col} \\ \text{of } D\bar{f}(\bar{x})}} g_j(\bar{x}) + \sum_{j=1}^m f_j(\bar{x}) \underbrace{\frac{\partial g_j}{\partial x_i}(\bar{x})}_{\substack{\text{ith col of} \\ D\bar{g}(\bar{x})}}$$

$$= \underbrace{D_{x_i} \bar{f}(\bar{x})}_{1 \times m} \cdot \underbrace{\bar{g}(\bar{x})}_{1 \times m} + \bar{f}(\bar{x}) \cdot \underbrace{D_{x_i} \bar{g}(\bar{x})}_{1 \times m}$$

dot products

Special Note: Careful with products! The 2 above are symmetric:  $f(\bar{x}) \cdot g(\bar{x}) = g(\bar{x}) \cdot f(\bar{x})$ .

If the product is not symmetric, then neither is the Product Rule:

ex. Cross product in  $\mathbb{R}^3$ :  $\vec{a} \times \vec{b} \neq \vec{b} \times \vec{a}$  in general.

actually antisymmetric  $\vec{a} \times \vec{b} = -\vec{b} \times \vec{a}$

Hence for  $\vec{f}, \vec{g}: X \subset \mathbb{R}^n \rightarrow \mathbb{R}^3$ , and  $\vec{h}(x) = \vec{f}(x) \times \vec{g}(x)$

$$\begin{aligned} D\vec{h}(x) &= D(\vec{f} \times \vec{g})(x) \\ &= D\vec{f}(x) \times \vec{g}(x) + \vec{f}(x) \times D\vec{g}(x) \end{aligned}$$

where  $D\vec{f}: X \subset \mathbb{R}^n \rightarrow \mathbb{R}^3$   
 $D\vec{g}$ .

Similar notions for Quotient Rule.

A note on partial derivatives

Given a real-valued  $f: X \subset \mathbb{R}^n \rightarrow \mathbb{R}$ , then

$$\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z}: X \rightarrow \mathbb{R}.$$

If all exist and are continuous in a nbhd of  $\vec{x}$ , then we say  $f$  is of class  $C^1$ , or  $f \in C^1$ .

Def ~~the~~ second partial of  $f$  wrt a variable  $x$  say,

$$\text{is one of } \frac{\partial}{\partial x} \left( \frac{\partial f}{\partial x} \right): X \rightarrow \mathbb{R}$$

$$\frac{\partial}{\partial x} \left( \frac{\partial f}{\partial y} \right): X \rightarrow \mathbb{R}$$

$$\frac{\partial}{\partial x} \left( \frac{\partial f}{\partial z} \right): X \rightarrow \mathbb{R}$$

Also written  $\frac{\partial^2 f}{\partial x^2}$ ,  $\frac{\partial^2 f}{\partial y \partial x}$ ,  $\frac{\partial^2 f}{\partial x \partial y}$ , or  $f_{xx}$ ,  $f_{xy}$ ,  $f_{yx}$   
notice the order

if all  $\partial^2 f$  exist and are continuous in a neighborhood of every  $\bar{x} \in \mathbb{X}$ , we say  $f \in C^2$ .

(\*)

Let  $f: \mathbb{X} \subset \mathbb{R}^n \rightarrow \mathbb{R}$ . For  $i_1, \dots, i_k \in \{1, \dots, n\}$   
the  $k$ th partial derivative of  $f$  with respect to  $x_{i_1}, \dots, x_{i_k}$  is

$$\frac{\partial^k f}{\partial x_{i_k} \dots \partial x_{i_1}}(\bar{x}) = \frac{\partial}{\partial x_{i_k}} \left( \dots \left( \frac{\partial f}{\partial x_{i_1}}(\bar{x}) \right) \dots \right)$$

or we write  $f_{x_{i_k} \dots x_{i_1}}$ .

ex  $f(x, y, z) = z \cos(2xy)$

$$f_x(x, y, z) = -z \sin(2xy) 2y = -2yz \sin(2xy)$$

$$f_y(x, y, z) = -2xz \sin(2xy)$$

$$f_z(x, y, z) = \cos(2xy)$$

$$\left\{ \begin{aligned} f_{xy}(x, y, z) &= \frac{\partial^2 f}{\partial y \partial x} = \frac{\partial}{\partial y} \left( \frac{\partial f}{\partial x} \right) = \frac{\partial}{\partial y} (-2yz \sin(2xy)) \\ &= -2z \sin(2xy) - 4xyz \cos(2xy) \\ f_{yx}(x, y, z) &= \frac{\partial^2 f}{\partial x \partial y} = \frac{\partial}{\partial x} \left( \frac{\partial f}{\partial y} \right) = \frac{\partial}{\partial x} (-2xz \sin(2xy)) \\ &= -2z \sin(2xy) - 4xyz \cos(2xy) \end{aligned} \right.$$

Notice these are equal!

it turns out, this is always true when  $f \in C^2$ : VI

Then Suppose  $f: X \subset \mathbb{R}^n \rightarrow \mathbb{R}$  is  $C^2$  on an open  $X$ .

Then for any choice of  $i_1, i_2 \in \{1, \dots, n\}$ ,

$$\frac{\partial^2 f}{\partial x_{i_1} \partial x_{i_2}} = \frac{\partial^2 f}{\partial x_{i_2} \partial x_{i_1}}$$

The proof is constructive. We won't do it in class.

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Def  $f: X \subset \mathbb{R}^n \rightarrow \mathbb{R}$  is of class  $C^n$ ,  $n \in \mathbb{N}$  if it has continuous partial derivatives up to and including order  $n$ .  $\vec{g}: X \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$  is of class  $C^n$  if each  $g_i: X \rightarrow \mathbb{R}$  is of class  $C^n$ .

A function like above is called  $C^\infty$  or smooth if it has continuous partials of all orders.

Notes ① This should be obvious, but if  $f \in C^k$ , then  $f \in C^l \quad \forall l < k$ .

② A continuous func is called  $C^0$ .

Something to think about

For  $f: \mathbb{R}^n \rightarrow \mathbb{R}$ , suppose  $f$  is  $C^\infty$ .

- Then we know
- ①  $f$  has  $n$  1<sup>st</sup> partials
  - ②  $f$  has  $n^2$  2<sup>nd</sup> partials  
(each 1<sup>st</sup> partial is a diff. func of  $n$ -variables, so it has  $n$ -derivatives of its own.)
  - ③  $f$  has  $n^k$   $k$ th partials,  $\forall k \in \mathbb{N}$ .

Now  $Df(x)$  is a row matrix with  $n$  entries, each a ~~func~~ real-valued function on  $n$  vars.

Each of these funcs is differentiable, and if we view them as elements of a column, then

$$Df: \mathbb{R}^n \rightarrow \mathbb{R}^n.$$

And  $D(Df) = D^2f(x)$  will be a  $n \times n$  matrix of functions, each real valued and diff.

And if each of the entries of  $D^2 f(x)$ ,  
 $\frac{\partial^2 f}{\partial x_i \partial x_j}$  is diff, each has its own derivatives  
of its own, then one can think of  
 $D^2 f(x)$  as a function on  $\mathbb{R}^n$ . What is  
its codomain?

What is its derivative? What kind of object is  
 $D(D^2 f)(x) = D^3 f(x)$ ?

What about  $D^k f(x)$ ,  $k \in \mathbb{N}$ ?

These objects will play a role in the  
multivariable Taylor expansion of a func.

Think about this, ~~!~~