

Lecture 4.

I

Examples of metrics ~~metrics~~ in \mathbb{R}^n include:

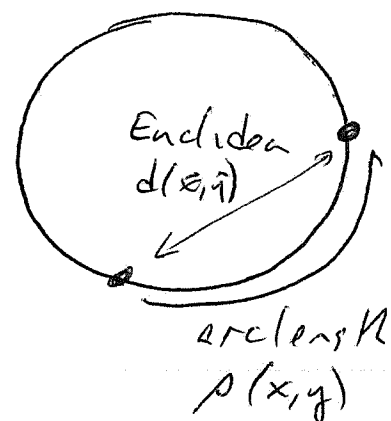
- Euclidean: $d(\vec{x}, \vec{y}) = \sqrt{\sum_{i=1}^n (x_i - y_i)^2}$
- Manhattan: $d(\vec{x}, \vec{y}) = \sum_{i=1}^n |x_i - y_i|$
(taxicab)
- Maximum: $d(\vec{x}, \vec{y}) = \max_i |x_i - y_i|$

ex. On a circle of radius r in \mathbb{R}^2 , 2 metrics that are easy to "see":

Here, for x, y antipodal pts:

$$d(\vec{x}, \vec{y}) = 2r$$

$$\rho(x, y) = \pi r$$



With a metric on \mathbb{X} , one can define an open and closed ball in \mathbb{X} :

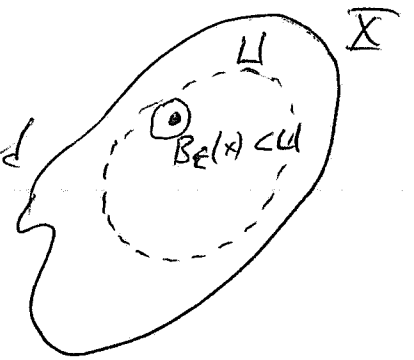
open $B_r(x) = \{y \in \mathbb{X} \mid d(x, y) < r\}$

closed $\overline{B}_r(x) = \{y \in \mathbb{X} \mid d(x, y) \leq r\}$

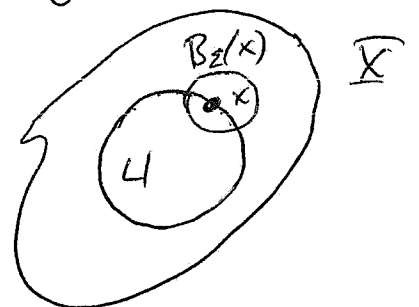
Note: We call these r -balls because in the Euclidean metric they look like n -dimensional balls, with spheres as skins. But in different metrics, balls (circles) will not look round! See the text exercises 29 and 30.

With the definition of an r -ball, we can define small open and closed sets, and neighborhoods:

Def. A subset $U \subset X$ is called open if $\forall x \in U, \exists \varepsilon > 0$
 $\Rightarrow B_\varepsilon(x) \subset U$.



Def. A pt $x \in X$ is a boundary pt of a subset $U \subset X$ if $\forall \varepsilon > 0, B_\varepsilon(x)$ contains at least one pt ~~in~~ U and at least one pt not in U .



Defn A subset $U \subset \mathbb{X}$ is called closed in \mathbb{X} if every boundary pt of U is an element of U .

Def A subset $U \subset \mathbb{X}$ is called a neighborhood of a point $x \in \mathbb{X}$ if $\exists \varepsilon > 0$ where $B_\varepsilon(x) \subset U$.

Def. The set of all boundary pts of a subset $U \subset \mathbb{X}$ is called the boundary of U and denoted ∂U .

Find notes on metrics

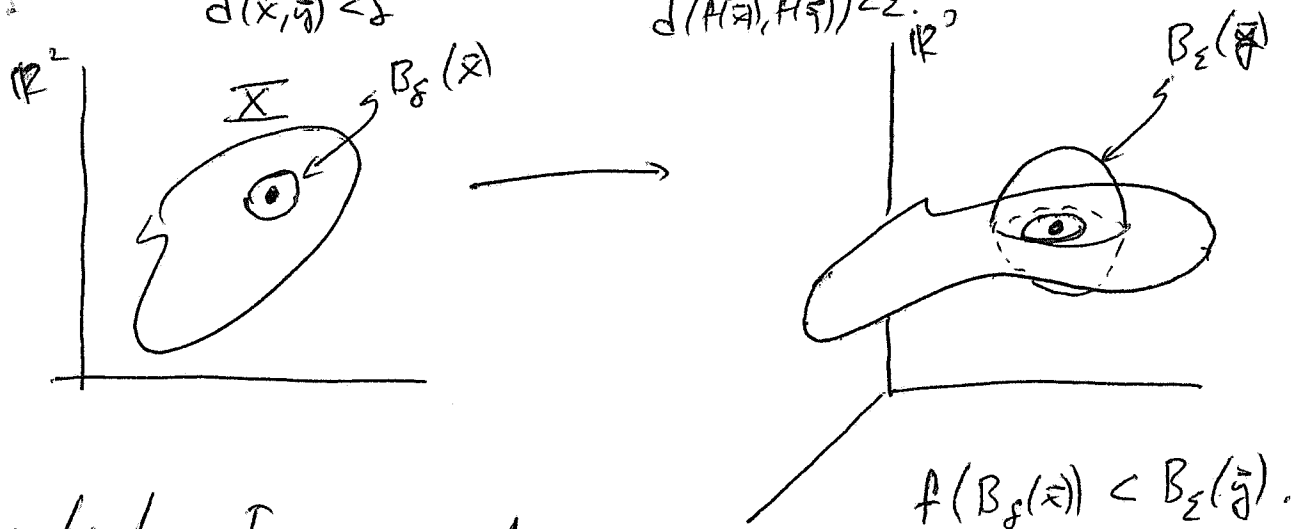
- ① A set w/ a metric on it is called a metric space.
- ② Any subset of a metric space is a metric space.
- ③ If $\mathbb{X} \subset \mathbb{R}^n$, we can always assume that it is a metric space.

Recall the definition of (function) continuity from vector calculus:

$f: X \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$ is continuous at $x \in X$ if $\forall \epsilon > 0, \exists \delta > 0 \Rightarrow$ if

$$\| \vec{x} - \vec{y} \| < \delta, \text{ then } \| f(\vec{x}) - f(\vec{y}) \| < \epsilon$$

$$d(\vec{x}, \vec{y}) < \delta \quad d(f(\vec{x}), f(\vec{y})) < \epsilon$$



In calculus I, $m=n=1$ and the metrics were the same.

In vector calculus, the metrics in the above def are different:

$$d(\vec{x}, \vec{y}) = d_{\mathbb{R}^n}(\vec{x}, \vec{y})$$

$$d(f(\vec{x}), f(\vec{y})) = d_{\mathbb{R}^m}(f(\vec{x}), f(\vec{y}))$$

New def A ~~map~~ function $f: X \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$
 is called Lipschitz cont, with constant λ ,
 or λ -Lipschitz, if

$$d(f(x), f(y)) \leq \lambda d(x, y) \quad \forall x, y \in X$$

Notes ① λ is a bound on the stretching ability
 of f on X .

② Lipschitz continuity is "stronger" than
 continuity. (if f is Lip cont. $\Rightarrow f$ is cont.)

③ Obvious? that $\lambda \geq 0$

④ if f is λ_0 -Lipschitz, then f is λ -Lip
 for all $\lambda > \lambda_0$. So

define
$$\text{Lip}(f) = \sup_{x \neq y} \frac{d(f(x), f(y))}{d(x, y)}$$

as the best one.

ex. $f(x) = \frac{1}{x}$ is Lipschitz cont on any domain (a, b) , where $0 < a \leq b < \infty$, but not on $(0, b)$ for any $b > 0$.

ex. $h(x) = |x|$ is Lipschitz cont on \mathbb{R} .

What is $\text{Lip}(h)$?

ex. ~~Polynomials~~ ^{$n \geq 1$} degree polynomials are never Lip cont on infinite length intervals and always Lip cont on finite length ones.

Notice Let $f: \mathbb{R} \rightarrow \mathbb{R}$ be L -Lipschitz. Then

the condition is $|f(x) - f(y)| \leq L|x - y| \quad \forall x, y \in \mathbb{R}$.

and then for $x \neq y$, $\frac{|f(x) - f(y)|}{|x - y|} \leq L$.

If f is diff. at x , then LHS limits to $|f'(x)|$ as $y \rightarrow x$.

\implies For diff. functions, the Lip. constant bounds the derivative! (even tho Lip cont requires no der)

We use this

Prop Let $f: I \subset \mathbb{R} \rightarrow \mathbb{R}$ be C^1 on an open I ,
where $\forall x \in I, |f'(x)| \leq \lambda$.

$\implies f$ is λ -Lipschitz

pf. This is just an application of the MVT.

$$d(f(x), f(y)) = |f(x) - f(y)| \stackrel{\text{MVT}}{=} |f'(c)| |x - y|$$

for some $c \in (x, y)$, and

$$|f'(c)| |x - y| \leq \lambda |x - y| = \lambda d(x, y) \quad \square$$

Def A λ -Lipschitz function $f: X \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$
on a metric space X is called a contraction
if $\lambda < 1$.

For our purposes, we will always assume codomains
and domains are the same!

ex. The map $f: \mathbb{R} \rightarrow \mathbb{R}$, $f(x) = e^k x$, $k < 0$
 (this is the time-1 map of $\dot{x} = kx$), is a
 contraction, with $\lambda = e^k < 1$.

ex. $g(x) = \sqrt{x}$ is a contraction on $(1, \infty)$.
 What is $\text{Lip}(g)$ here? $\lambda = \frac{1}{2}$.

Prop Let f be C^1 on a closed, bounded interval,
 with $|f'(x)| < 1 \quad \forall x \in I \Rightarrow f$ is a contraction.

pt. f' is continuous on I , so by EVT will
 achieve its max. at $\lambda_m < 1$. By previous

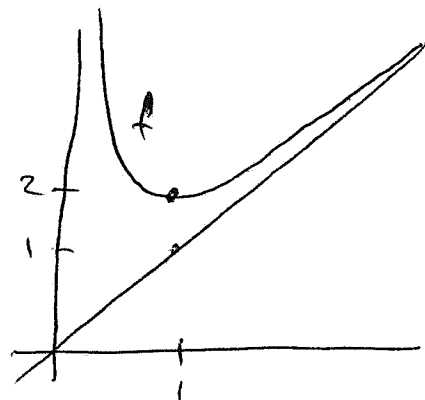
prop then f is λ_m -Lipschitz. \square

Note: Closed and bounded are both vital for
 this to be true.

Closed, not bdd counter example

$$f(x) = x + \frac{1}{x} \text{ on } I = [1, \infty)$$

why not?



bdd but not closed counter example

$$g(x) = 2\sqrt{x} \text{ on } (1, b) \text{ for any } b > 4$$

(why must we need $b > 4$ here?).

Lipschitz cont says a lot about how fast the images of pts can move away from each other (exponential at best!!), since

$$d(A^2(x), A^2(y)) \leq \lambda d(A(x), A(y)) \leq \lambda(\lambda d(x, y)) = \lambda^2 d(x, y).$$

$$d(A^n(x), A^n(y)) \leq \lambda^n d(x, y), \quad n \in \mathbb{N}.$$

And if $\lambda < 1$... ? For a contraction??

This is tailor made for studying orbit behavior!

The Contraction Principle

Thm Let $I \subset \mathbb{R}$ be closed and $f: I \rightarrow I$ a contraction. Then f has a unique fixed pt x_0 , and $\forall x \in I$,

$$|f^n(x) - x_0| \leq \lambda^n |x - x_0|$$

Notes ① Thus $\forall x \in I$, $\mathcal{O}_x \rightarrow x_0$ exponentially due to λ^n , $0 < \lambda < 1$.

② For now, only valid in \mathbb{R} .

③ To show this, we will need the idea of a sequence in \mathbb{R} ~~being~~ being Cauchy.

Def. For $N \in \mathbb{N}$, a sequence $\{x_i\}_{i=1}^{\infty}$ in \mathbb{R}^N is called Cauchy if $\forall \varepsilon > 0, \exists A > 0 \rightarrow \forall m, n \geq A, d(x_m, x_n) < \varepsilon$.