

Learning interacting kernels in mean-field equations of particle systems

Fei Lu

Department of Mathematics, Johns Hopkins University

Joint with **Quanjun Lang**

August 23, 2021;
Dynamics Days Europe 2021, Nice, France



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Outline

- 1 Motivation and problem statement
- 2 Nonparametric learning
- 3 Numerical examples

An inverse problem

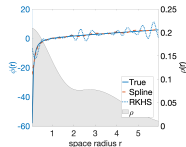
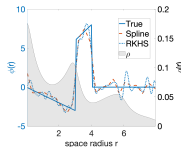
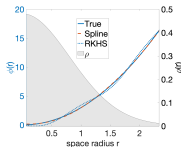
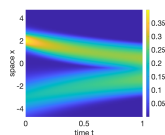
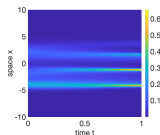
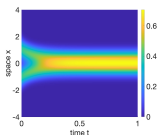
Mean-field equation of interacting particles

$$\partial_t u = \nu \Delta u + \nabla \cdot [u(K_\phi * u)], \quad x \in \mathbb{R}^d, t > 0,$$

where $K_\phi(x) = \nabla(\Phi(|x|)) = \phi(|x|)\frac{x}{|x|}$.

Question: identify ϕ from discrete data $\{u(x_m, t_l)\}_{m,l=1}^{M,L}$?

Data



Kernel ϕ ?

Motivation

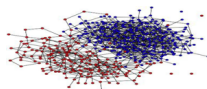
Systems of interacting particles/agents

$$\frac{d}{dt} X_t^i = \frac{1}{N} \sum_{i'=1}^N \phi(|X_t^j - X_t^{i'}|) \frac{X_t^j - X_t^{i'}}{|X_t^j - X_t^{i'}|} + \sqrt{2\nu} dB_t^i, \quad i = 1, \dots, N$$

- X_t^i : the i -th particle's position; B_t^i : Brownian motion
- From Newton's law (2nd-order) + 0-mass \rightarrow 1st-order
- Applications in many disciplines:
 - Statistical physics, quantum mechanics
 - Biology [Keller-Segal1970, Cucker-Smale2000]
 - Social science [Motsch-Tadmor2014]
 - Monte Carlo sampling [Del Moral13]
 - Epidemiology (Agent-based models for COVID19 at Imperial)



Popkin. Nature(2016)



Voter model (wiki)



Previous work: finite N

Maggioni et al: [Maggioni, L., Tang, Zhong, Miller, Li, Zhang: PNAS19, SPA20, et al]

- Data: many trajectories $\{X_{[0,T]}^{(m)}\}_{m=1}^M$.
- Nonparametric learning
 - ▶ Identifiability: $L^2(\rho_T)$ with $\rho_T \leftarrow |X_t^j - X_t^i|$
 - ▶ minimax convergence rate
 - ▶ various systems: Opinion Dynamics, Lennard-Jones, Prey-Predator

Large system challenge: $N \rightarrow \infty$

Data at macroscopic scale:

- lack of trajectories $\{X_{[0,T]}^{(m)}\}_{m=1}^M$ (recall $X_t \in \mathbb{R}^{Nd}$)
- only population density $u(x, t) = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=1}^N \delta(X_t^i - x)$

Discrete in space-time: $\{u(x_m, t_l)\}_{m,l=1}^{M,L}$

\Rightarrow Infer kernel ϕ in Mean-field equation:

$$\partial_t u = \nu \Delta u + \nabla \cdot [u(K_\phi * u)]$$

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 - ▶ A probabilistic loss functional
 - ▶ Identifiability: function spaces of learning
 - ▶ Rate of convergence
- 3 Numerical examples

Variational approach: minimize a loss functional $\mathcal{E}(\psi)$

$$\partial_t u = \nu \Delta u + \nabla \cdot [u(K_\psi * u)]$$

Loss functions that do not work

- discrepancy: $\mathcal{E}(\psi) = \|\partial_t u - \nu \Delta u - \nabla \cdot (u(K_\psi * u))\|^2$
derivatives approx. from discrete data
- Free energy: $\mathcal{E}(\psi) = C + |\int_{\mathbb{R}^d} u[(\Psi - \Phi) * u] dx|^2$
limited information from the 1st moment
- Wasserstein-2: $\mathcal{E}(\psi) = W_2(u^\psi, u)$
costly: require many PDE simulations in optimization

A probabilistic loss functional

$$\mathcal{E}(\psi) := \frac{1}{T} \int_0^T \int_{\mathbb{R}^d} \left[|K_\psi * u|^2 u - 2\nu u (\nabla \cdot K_\psi * u) + 2\partial_t u (\Psi * u) \right] dx dt$$

- = $-\mathbb{E}[\text{log-likelihood}]$ of the process

$$\begin{cases} d\bar{X}_t = -K_{\phi_{true}} * u(\bar{X}_t, t) dt + \sqrt{2\nu} dB_t, \\ \mathcal{L}(\bar{X}_t) = u(\cdot, t), \end{cases}$$

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- Derivative-in-space free!
- Suitable for high-dimension: $K_\psi * u(\bar{X}_t) = \mathbb{E}[K_\psi(\bar{X}_t - \bar{X}'_t) | \bar{X}_t]$

$$\mathcal{E}(\psi) = \frac{1}{T} \int_0^T \left(\mathbb{E}|K_\psi * u(\bar{X}_t)|^2 + \partial_t \mathbb{E}\Psi(\bar{X}_t - \bar{X}'_t) + 2\nu \mathbb{E}[\Delta\Psi(\bar{X}_t - \bar{X}'_t)] \right) dt$$

Least squares estimator

$$\begin{aligned}\mathcal{E}(\psi) &:= \frac{1}{T} \int_0^T \int_{\mathbb{R}^d} \left[|K_\psi * u|^2 u - 2\nu u (\nabla \cdot K_\psi * u) + 2\partial_t u (\Psi * u) \right] dx dt \\ &= \langle \psi, \psi \rangle - 2 \langle \psi, \phi \rangle\end{aligned}$$

- bilinear form $\langle \phi, \psi \rangle = \frac{1}{T} \int_0^T \int_{\mathbb{R}^d} \langle (K_\phi * u), (K_\psi * u) \rangle u(x, t) dx dt$

- Hypothesis space $\mathcal{H}_n = \text{span}\{\phi_i\}_{i=1}^n$: $\psi = \sum_{i=1}^n c_i \phi_i$

$$\Rightarrow \mathcal{E}(\psi) = \mathbf{c}^\top \mathbf{A} \mathbf{c} - 2\mathbf{b}^\top \mathbf{c} \text{ with } A_{ij} = \langle \phi_i, \phi_j \rangle$$

$$\Rightarrow \text{Estimator: } \hat{\phi}_n = \sum_{i=1}^n \hat{c}_i \phi_i, \quad \hat{\mathbf{c}} = \mathbf{A}^{-1} \mathbf{b}$$

- From data $\{u(x_m, t_l)\}_{m,l=1}^{M,L}$:

$$\hat{\phi}_{n,M,L} = \sum_{i=1}^n \hat{\mathbf{c}}_{n,M,L}^i \phi_i, \quad \text{with } \hat{\mathbf{c}}_{n,M,L} = \mathbf{A}_{n,M,L}^{-1} \mathbf{b}_{n,M,L}.$$

Three fundamental issues

- Identifiability: uniqueness of minimizer, A^{-1}
- Choice of \mathcal{H}_n : B-splines $\{\phi_i\}_{i=1}^n$ and n ?
- Convergence rate when $\Delta x = M^{-1/d} \rightarrow 0$?

Identifiability and function space of learning

Recall that $\mathcal{H} = \text{span}\{\phi_i\}_{i=1}^n$,

$$A_{ij} = \langle\langle \phi_i, \phi_j \rangle\rangle, \quad \langle\langle \phi, \psi \rangle\rangle = \int_{\mathbb{R}^+} \int_{\mathbb{R}^+} \phi(r)\psi(s)\bar{R}_T(r, s)\rho_T(dr)\rho_T(ds)$$

- **identifiability: on RKHS** $H_{\bar{R}} \subset L^2(\rho_T)$ [LangLu21]
- Positive compact operator $L_{\bar{R}_T}$
 - ▶ normal matrix $A = L_{\bar{R}_T}|_{\mathcal{H}}$ in $L^2(\rho_T)$

$$c_{\mathcal{H}, T} = \inf_{\psi \in \mathcal{H}, \|\psi\|_{L^2(\rho_T)}=1} \langle\langle \psi, \psi \rangle\rangle > 0 \quad (\text{Coercivity condition})$$

- ▶ $H_{\bar{R}}$ based Regularization needed as $\text{Dim}(\mathcal{H}) \uparrow \infty$.

Integration Error bounds

$$\mathbb{H} = L^2(\rho_T)$$

Theorem (Lang-Lu20)

Let $\mathcal{H} = \text{span}\{\phi_i\}_{i=1}^n$ and $\hat{\phi}_n$ the projection of ϕ on $\mathcal{H} \subset \mathbb{H}$. Assume regularity conditions. Then

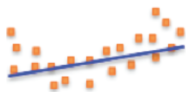
$$\|\hat{\phi}_{n,M,L} - \hat{\phi}_n\|_{\mathbb{H}} \leq 2c_{\mathcal{H},T}^{-1} (C^b \sqrt{n} + C^A n \|\phi\|_{\mathbb{H}}) (\Delta x^\alpha).$$

- Δx^α comes from numerical integrator (Riemann sum)
- Dominating order: $n\Delta x^\alpha$

Optimal dimension and rate of convergence

Total error: trade-off

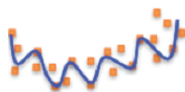
$$\|\hat{\phi}_{n,M,\infty} - \phi\|_{\mathbb{H}} \leq \underbrace{\|\hat{\phi}_{n,M,\infty} - \hat{\phi}_n\|_{\mathbb{H}}}_{\text{integration error}} + \underbrace{\|\hat{\phi}_n - \phi\|_{\mathbb{H}}}_{\text{approximation error}}$$



Underfitting



Balanced



Overfitting

Theorem (Lang-Lu20)

Assume $\|\hat{\phi}_{n,M,\infty} - \hat{\phi}_n\|_{\mathbb{H}} \lesssim n(\Delta x)^\alpha$ and $\|\hat{\phi}_n - \phi\|_{\mathbb{H}} \lesssim n^{-s}$. Then, with dimension $n \approx (\Delta x)^{-\alpha/(s+1)}$, we have minimax rate:

$$\|\hat{\phi}_{n,M,\infty} - \phi\|_{\mathbb{H}} \lesssim (\Delta x)^{\alpha s/(s+1)}$$

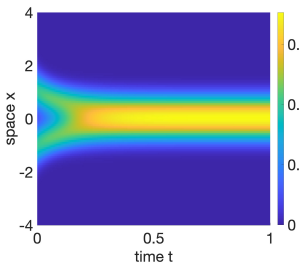
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 - ▶ A probabilistic loss functional
 - ▶ Identifiability: RKHS
 - ▶ Rate of convergence
- 3 Numerical examples
 - ▶ Granular media: smooth kernel $\phi(r) = 3r^2$
 - ▶ Opinion dynamics: piecewise linear ϕ
 - ▶ Repulsion-attraction: singular $\phi = r - r^{-1.5}$

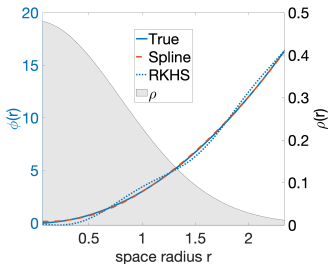
Example 1: granular media

$$\phi(r) = 3r^2$$

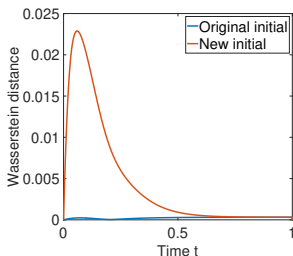
$$\partial_t u = \nu \Delta u + \nabla \cdot [u(K_\phi * u)], \quad x \in \mathbb{R}^d, t > 0, \quad K_\phi(x) = \phi(|x|) \frac{x}{|x|}$$



The solution $u(x, t)$

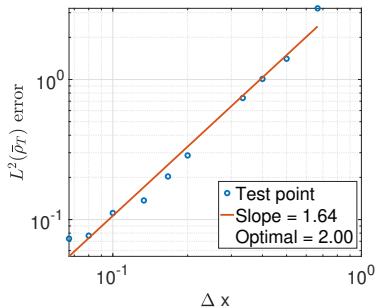
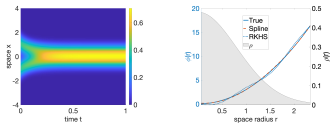


Estimators of ϕ

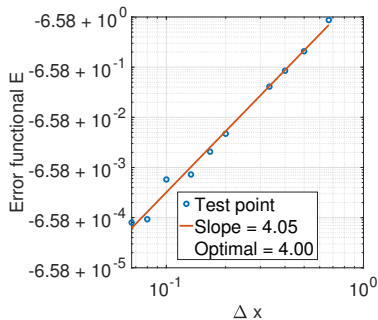


Wasserstein $W_2(u, \hat{u})$

Example 1: granular media



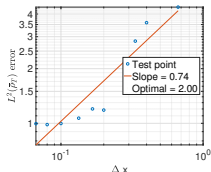
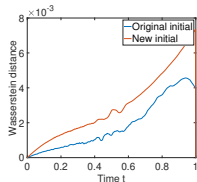
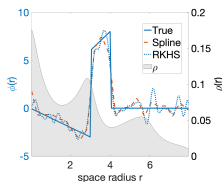
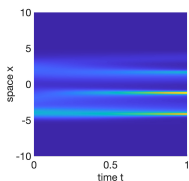
Convergence rate of $L^2(\rho_T)$ error
close to optimal



Convergence rate of $\mathcal{E}_{M,L}$

Example 2: Opinion dynamics

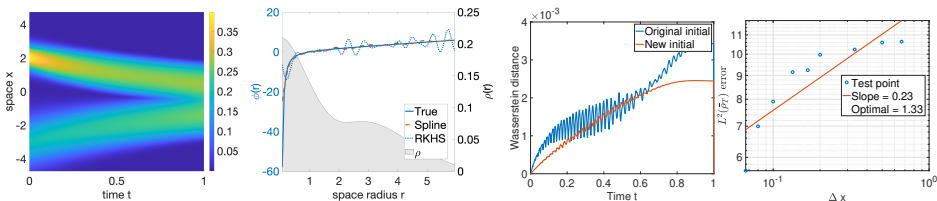
$\phi(r)$ piecewise linear



- Acceptable estimator
- Accurate prediction: small Wasserstein-2
- sub-optimal rate ($\phi \notin W^{1,\infty}$)

Example 3: repulsion-attraction

$$\phi(r) = r - r^{-1.5} \text{ (singular)}$$



- Acceptable estimator
- Accurate prediction: small Wasserstein-2
- low rate: theory does not apply

Summary and open problems

Problem: Estimate ϕ of Mean-field equation

$$\partial_t u = \nu \Delta u + \nabla \cdot [u(K_\phi * u)]$$

from discrete data $\{u(x_m, t_l)\}_{m,l=1}^{M,L}$.

Solution: [Least-squares-based algorithm](#)

- A probabilistic loss functional

Theory:

- Identifiability: intrinsic RKHSs
- Minimax convergence rate

Future directions

- General systems/settings:
 - ▶ 2nd-order systems / inviscid equations
 - ▶ High-dimensional cases (Monte Carlo)
- System-Intrinsic Data-Adaptive RKHSs:
 - ▶ Spare-aware regularization
 - ▶ feature selection

References (@ <http://www.math.jhu.edu/~feilu>)

- Q. Lang and F. Lu. Learning interaction kernels in mean-field equations of 1st-order systems of interacting particles. arXiv.2010.15694

- Q. Lang and F. Lu. Identifiability of interaction kernels in mean-field equations of interacting particles. arXiv2106.