

The Change of variables formula
for one variable Calculus integrals

$$(*) \quad A(t) := \int_a^t f(\varphi(x)) \varphi'(x) dx = \int_{\varphi(a)}^{\varphi(t)} f(x) dx =: B(t)$$

skip
proof

is easily established. Given
 f continuous and $\varphi \in C^1$, using
the fundamental theorem and the
chain rule, we find

$$A'(t) = f(\varphi(t)) \varphi'(t) = B'(t).$$

But $A(a) = B(a) = 0 \Rightarrow A(t) \equiv B(t)$

what is the analogue of 2
(*) for multiple integrals?

Consider the case $n=2$ and
let D be a "nice" bounded
open region in the x, y plane

(perhaps elementary) and

Similarly D^* a "nice"
bounded region in the u, v
plane.

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Further let $T: D^* \rightarrow D$
be of class C^1 (continuously
differentiable map) which is
one to one and onto ($D = T(D^*)$)

so $T(u, v) = (x(u, v), y(u, v))$

Then for any integrable
(say continuous) function on D

$$\iint_D f(x, y) dx dy = \iint_{D^*} f(x(u, v), y(u, v)) \cdot \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv$$

Here $\frac{\partial(x, y)}{\partial(u, v)} = \det \begin{pmatrix} x_u & x_v \\ y_u & y_v \end{pmatrix} = x_u y_v - x_v y_u$

$= \det(DT(u, v))$ is the

Jacobian, ^{determinant} of the mapping T and (4)
 $\left| \frac{\partial(x,y)}{\partial(u,v)} \right|$ is its absolute value

The proof of this theorem
will be sketched next

lecture. For the moment,

we focus on the geometry

of maps from $\mathbb{R}^2 \rightarrow \mathbb{R}^2$

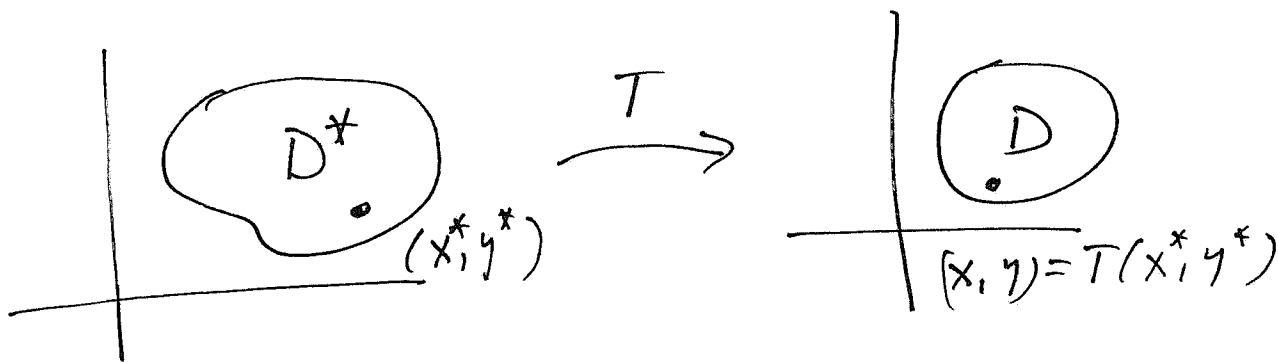
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(5)

Maps from \mathbb{R}^2 to \mathbb{R}^2

Let $T: D^* \subset \mathbb{R}^2 \rightarrow \mathbb{R}^2$

be a nice map (C^1)



Example 1 Let $D^* = [0, 1] \times [0, 2\pi]$
be a rectangle in (r, θ) space,
 $0 \leq r \leq 1$, $0 \leq \theta \leq 2\pi$ (polar coord.
space). Let T be the
polar coordinate "change of variables"

$$T(r, \theta) = (r \cos \theta, r \sin \theta) = (x, y) \quad \text{⑥}$$

where (x, y) are cartesian coordinates

$$\text{Since } x^2 + y^2 = r^2 (\cos^2 \theta + \sin^2 \theta) = r^2,$$

the image $T(D^*) \subset$ unit disk
(since $0 \leq r \leq 1$). On the

other hand every pt (x, y) in the

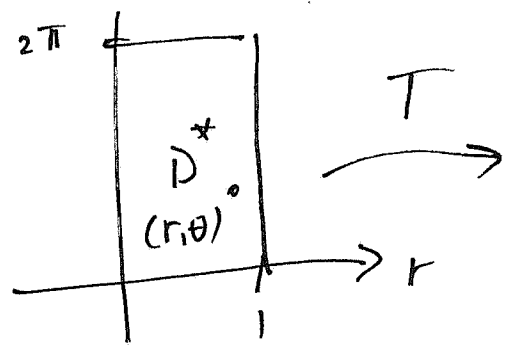
unit disk can be written as

$$x = r \cos \theta, y = r \sin \theta \quad \text{for some}$$

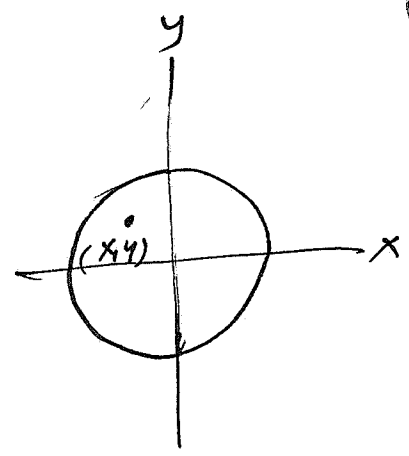
$$0 \leq r \leq 1, \quad 0 \leq \theta \leq 2\pi \quad \text{so}$$

The map T is onto the unit disk.

Note $\frac{\partial(x, y)}{\partial(r, \theta)} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ -\sin \theta & r \cos \theta \end{vmatrix} = r$



T



Example 2 Let $T(x, y) = \begin{pmatrix} u \\ v \end{pmatrix} = \begin{pmatrix} \frac{x+y}{2} \\ \frac{x-y}{2} \end{pmatrix}$

$D^* = [-1, 1] \times [-1, 1] \subset \mathbb{R}^2$, the square of side length 2 centered at (0, 0)

What is $D = T(D^*)$?

Remark Note that T is a linear map from \mathbb{R}^2 with coordinates (x, y) to \mathbb{R}^2 with

coordinates (u, v)

with coordinates (u, v)

So is represented by the 2×2

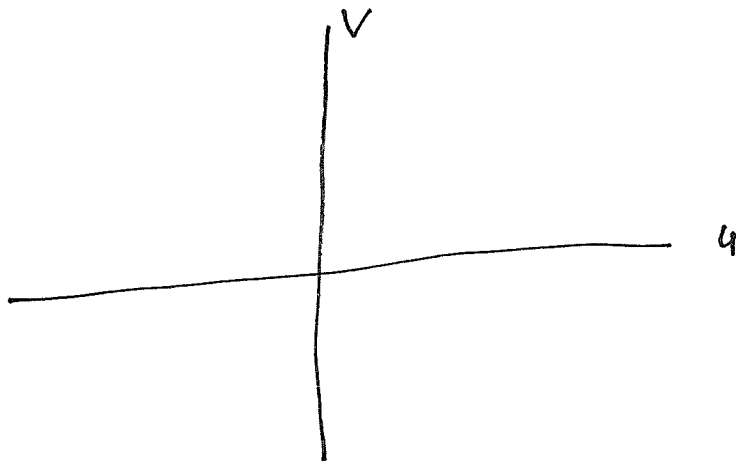
matrix $A = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{bmatrix}$ (i.e. $T(x, y) = A \begin{pmatrix} x \\ y \end{pmatrix}$ written as a column vector,

The first column of A is $T\vec{i}$
 $= T(1, 0)$. The second column

is $T\vec{j} = T(0, 1)$. (Note also

that because T is linear

$$A = JT \text{ is constant}$$

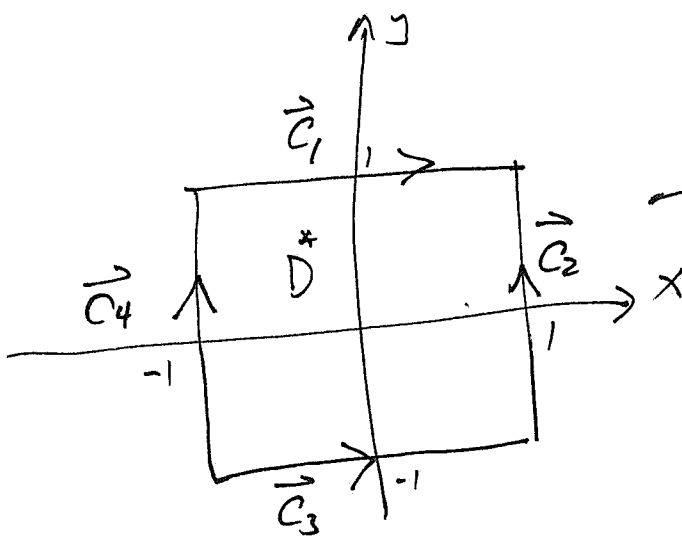


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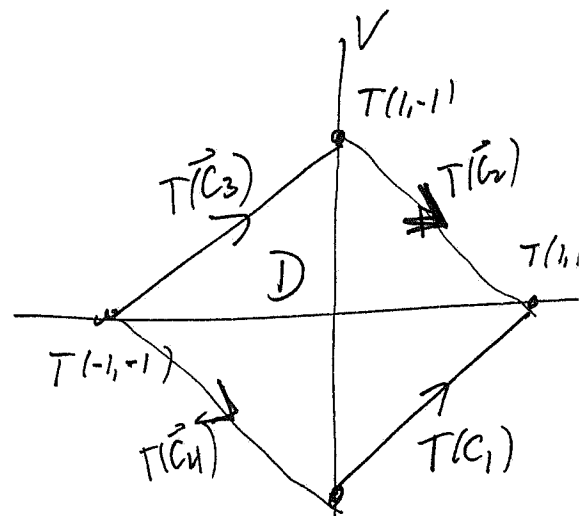
Example 2 (continued)

$$\text{Let } T(x, y) = \left(\frac{x+y}{2}, \frac{x-y}{2} \right) = (u, v)$$

$$D^* = [-1, 1] \times [-1, 1]$$



T



$$T(\vec{c}_1(t)) = \left(\frac{t+1}{2}, \frac{t-1}{2} \right)$$

$$-1 \leq t \leq 1$$

parametrization of

$$v - u = -1$$

$$T(\vec{c}_3(t)) = \left(\frac{t-1}{2}, \frac{t+1}{2} \right)$$

$$\vec{c}_1(t) = (t, 1), -1 \leq t \leq 1$$

$$\vec{c}_2(t) = (1, t), -1 \leq t \leq 1$$

$$\vec{c}_3(t) = (t, -1), -1 \leq t \leq 1$$

$$\vec{c}_4(t) = (-1, t), -1 \leq t \leq 1$$

Linear and affine maps from $\mathbb{R}^2 \rightarrow \mathbb{R}^2$

Defn' We say T is linear if

$$T(\vec{x}_1 + \vec{x}_2) = T\vec{x}_1 + T\vec{x}_2$$

$$T(c\vec{x}) = cT(\vec{x}) \quad c \in \mathbb{R}$$

Thus if T is defined on \mathbb{R}^2
with coordinates (x_1, x_2) , we can

represent T by a matrix

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

and $T(x_1, x_2) = (ax_1 + bx_2, cx_1 + dx_2)$

$$= \left(\text{Transpose } \uparrow \right) A \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

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(Note the columns of A
are $T\vec{e}_1$ and $T\vec{e}_2$)
 $\vec{e}_1 = \langle 1, 0 \rangle, \vec{e}_2 = \langle 0, 1 \rangle$

An affine map S from \mathbb{R}^2 to \mathbb{R}^2

is of the form $S(x_1, x_2) = T(x_1, x_2)$
 $+ (c_1, c_2)$

i.e. the composition of T with

a translation by (c_1, c_2) . Thus

we need only study T .

Important properties of linear maps

1. T linear maps lines to lines.

Let $\vec{c}(t) = \vec{x}_0 + t\vec{v}$. Then

$$T(\vec{c}(t)) = T(\vec{x}_0) + tT\vec{v} \quad \text{so}$$

the image of $\vec{c}(t)$ is a line through $T(\vec{x}_0)$ in the direction $T\vec{v}$

2. T is one to one
 if $\vec{x}_1 = \vec{x}_2$ then $T\vec{x}_1 = T\vec{x}_2$

2. Suppose the columns of A are linearly independent, i.e.

assume $\det A \neq 0$ ($\Leftrightarrow T\vec{e}_1, T\vec{e}_2$ linearly independent)

Then T is 1-1, i.e. $T\vec{x}_1 = T\vec{x}_2 \Rightarrow \vec{x}_1 = \vec{x}_2$

For since T is linear, $T(\vec{x}_1 - \vec{x}_2) = \vec{0}$
 $\vec{y}'' = (y_1, y_2)$

$\Leftrightarrow \begin{cases} ay_1 + by_2 = 0 \\ cy_1 + dy_2 = 0 \end{cases} \Leftrightarrow y_1 = y_2 = 0$

i.e. only trivial solutions of the homogeneous linear equations.

3. Again assuming $\det A \neq 0$

T is onto, that is

given $(u, v) \exists! x, y$ s. that

$$T(x, y) = (u, v) \iff$$

$$ax + by = u \quad ad - bc \neq 0$$

$$cx + dy = v$$

\rightarrow unique soln (x, y)

$$x = \frac{\begin{vmatrix} u & b \\ v & d \end{vmatrix}}{ad - bc}, \quad y = \frac{\begin{vmatrix} a & u \\ c & v \end{vmatrix}}{ad - bc}$$

(Cramer's rule)

In the previous example 2

$$\text{~~the~~ } u = \frac{x+y}{2}$$

$$v = \frac{x-y}{2}$$

we can invert T

$$x = u + v$$

$$y = u - v$$

Again assuming $\det A \neq 0$

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4. T maps parallelograms to parallelograms.

A parallelogram in the x, y plane

is of the form

$$\alpha \vec{v} + \beta \vec{w} + \vec{p}$$

$0 \leq \alpha, \beta \leq 1$
 \vec{v}, \vec{w} linearly independent

So $T(\alpha \vec{v} + \beta \vec{w} + \vec{p})$

$$= \alpha T\vec{v} + \beta T\vec{w} + T(\vec{p})$$

is again a parallelogram since

$$\det A \neq 0 \Rightarrow T\vec{v}, T\vec{w} \text{ linearly independent}$$

Example (degenerate linear)

$$T(x, y) = (x, 0) = (u, v)$$

$$T\vec{e}_1 = (1, 0) \quad T(\vec{e}_2) = (0, 0)$$

$$A = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \quad \det A = 0$$

T maps all of \mathbb{R}^2 onto the u axis of the image plane

Remark $T(x, y) = (ax + by, cx + dy)$
 $= (u, v)$

the Jacobian

$$JT = \begin{pmatrix} a & b \\ c & d \end{pmatrix} = A$$

constant

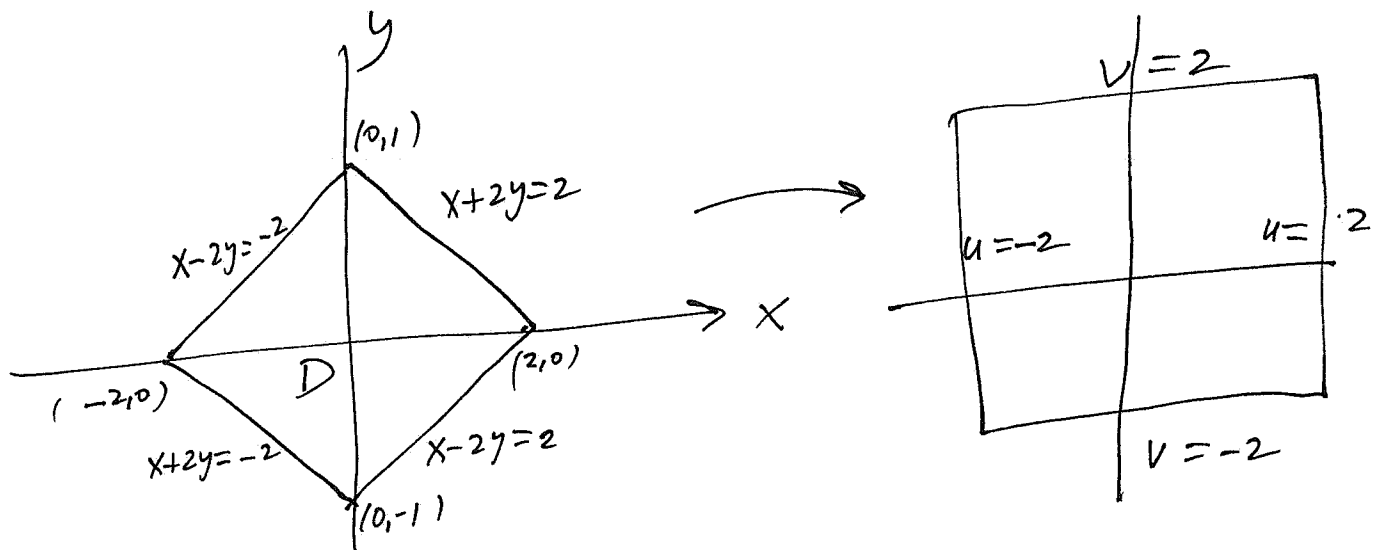
Example Map the region

D bounded by the lines

$$x+2y=2, \quad x-2y=2$$

$$x+2y=-2, \quad x-2y=-2$$

onto a square D^* centered at $(0,0)$ in the u,v plane.



It is natural to try the linear transformation

$$u = x + 2y$$

$$v = x - 2y$$

which maps the parallelogram D

1-1, onto the square D^* $-2 \leq u \leq 2$
 $-2 \leq v \leq 2$

Solving for the inverse transformation,

$$x = \frac{u+v}{2}, \quad y = \frac{u-v}{4}$$

Then
$$\frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{4} & -\frac{1}{4} \end{vmatrix} = -\frac{1}{4}$$

According to the change of variables theorem stated at the beginning, we can

evaluate $\iint_D (3x+6y)^2 dA$

$$= \iint_{D^*} \left(3\left(\frac{u+v}{2}\right) + 6\left(\frac{u-v}{4}\right) \right)^2 \cdot \left| -\frac{1}{4} \right| du dv$$

$$= \int_{-2}^2 \int_{-2}^2 9u^2 \cdot \frac{1}{4} du dv \quad (= 48)$$

Remark You can evaluate the original integral directly but it is much more work.

The change of variable formula
for double integrals

The change of variables formula
from Calculus I says:

$$(*) \quad A(t) = \int_{\varphi(a)}^{\varphi(t)} f(\varphi(x)) \varphi'(x) dx =$$

$$\int_{\varphi(a)}^{\varphi(t)} f(x) dx := B(t)$$

Here f is continuous and $\varphi \in C^1$

By the Fundamental theorem of
Calculus and the Chain Rule,

$$A'(t) \stackrel{\text{fund. thm}}{=} \int (\varphi(t)) \varphi'(t) \stackrel{\text{chain rule}}{=} B'(t)$$

(2)

But $A(a) = B(a) = 0$ so

$$A(t) = B(t)$$

What is the analogue of (*) for multiple integrals?

Consider the case $n=2$. Let D be a "nice" bounded open region in the x, y plane

Similarly let D^* be a "nice" bounded open region in the u, v plane. Further,

let $T: D^* \rightarrow D$ be a C^1 (continuously differentiable) mapping which is 1-1

and onto (so $D = T(D^*)$)

Write $T(u, v) = (x(u, v), y(u, v))$

and
$$\frac{\partial(x, y)}{\partial(u, v)} = \det \begin{pmatrix} x_u & x_v \\ y_u & y_v \end{pmatrix} = x_u y_v - x_v y_u.$$

Then for any integrable

$f: D \rightarrow \mathbb{R}$, we have

$$\iint_D f(x,y) dx dy = \iint_{D^*} f(x(u,v), y(u,v)) \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du dv$$

Example 1 The polar coordinate

map $x = r \cos \theta$ $y = r \sin \theta$ on

$$D^* = [0, 1] \times [0, 2\pi]$$

$$T(r, \theta) = (r \cos \theta, r \sin \theta) = (x, y)$$

and $D = T(D^*) = \{(x,y) : x^2 + y^2 \leq 1\}$

(5)

Then $\iint_D f(x, y) dx dy = \iint_{D^*} f(r \cos \theta, r \sin \theta) \cdot r dr d\theta$

If $f \equiv 1$ $A(D) = \int_0^{2\pi} \int_0^1 r dr d\theta = \pi$

Example 2 The density of an object occupying the upper

hemisphere $W = \{(x, y, z) : x^2 + y^2 + z^2 \leq 4, z \geq 0\}$

is $\rho(x, y, z) = z$. Find the

total mass of the object.

$$M = \iiint_W z dv = \iint_D \int_0^{\sqrt{1-x^2-y^2}} z dz dA$$

where $D = \{(x, y) : x^2 + y^2 \leq 1\}$

⑥

$$\text{Then } M = \iint_D \frac{1-x^2-y^2}{2} dA$$

Introduce polar coordinates

as in example 1. Then

$$M = \iint_{D^*} \frac{1-r^2}{2} \cdot r dr d\theta = \int_0^{2\pi} \int_0^1 \frac{1-r^2}{2} r dr d\theta$$

$$= 2\pi \cdot \frac{1}{2} \int_0^1 (r-r^3) dr = \pi \left(\frac{r^2}{2} - \frac{r^4}{4} \right) \Big|_{r=0}^{r=1}$$

$$= \frac{\pi}{4}$$

Example 4 Consider the

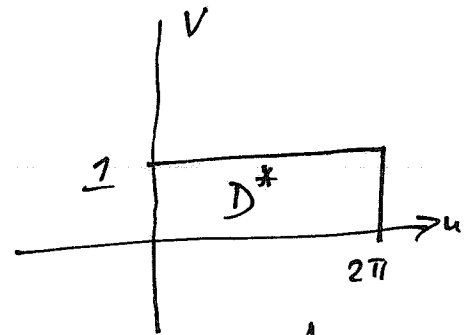
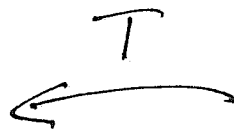
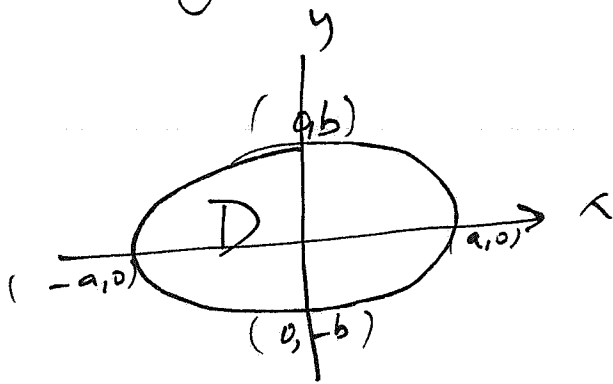
ellipse $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$ in the

x, y plane. Introduce the

change of variable

$$T: \begin{cases} x = a v \cos u \\ y = b v \sin u \end{cases}$$

$$D^* \begin{cases} 0 \leq u \leq 2\pi \\ 0 \leq v \leq 1 \end{cases}$$



Then

$$\frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} -av \sin u & a \cos u \\ bv \cos u & b \sin u \end{vmatrix}$$

$$= -abv$$

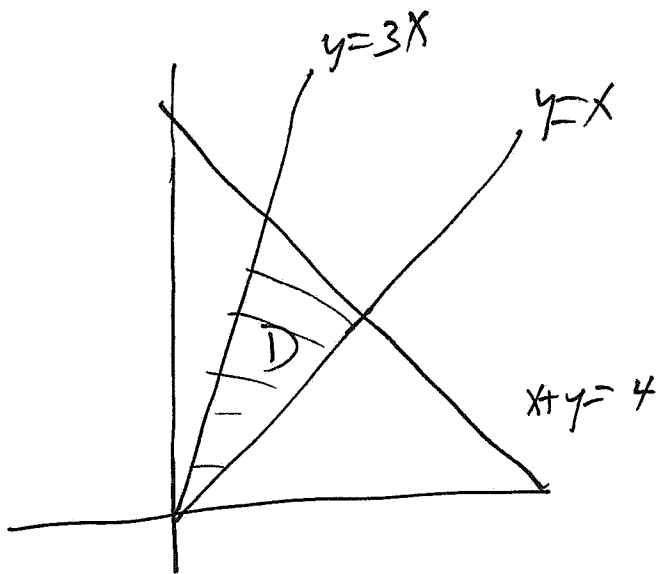
(8)

$$\text{Then } A(D) = \iint_{D^*} \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du dv$$

$$= ab \int_0^{2\pi} \int_0^1 v dv dy = ab \cdot 2\pi \cdot \frac{1}{2} = \pi ab$$

Example 5 Evaluate $\iint_D (x+y) dA$
 where D is the region bounded
 by the lines $y=x$, $y=3x$
 and $x+y=4$

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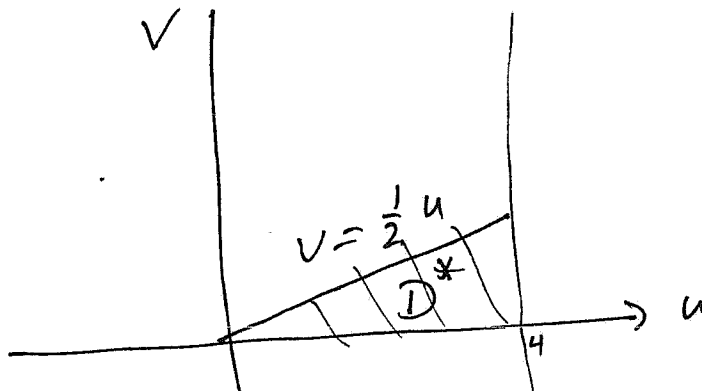
Let $T(u, v) = \left(\frac{u-v}{2}, \frac{u+v}{2} \right) = (x, y)$

Then $u = x + y$
 $v = y - x$

$y = 3x \iff \frac{u+v}{2} = \frac{3}{2}(u-v)$
 $\iff u = 2v \iff v = \frac{1}{2}u$

$y = x \iff v = 0$

$x+y=4 \iff u = 4$



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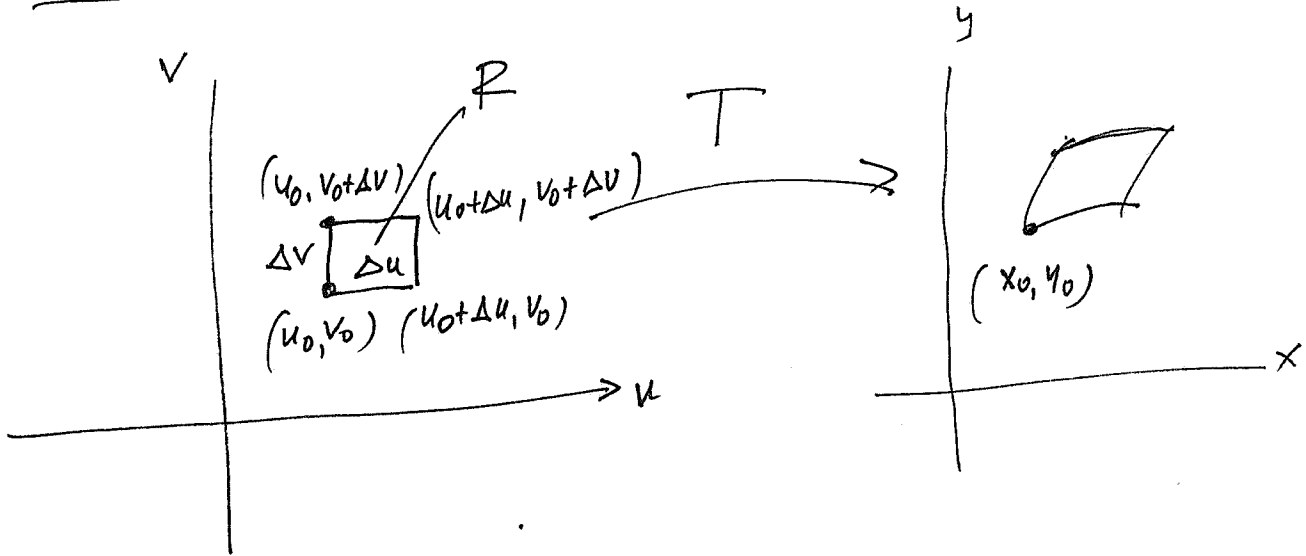
$$\frac{\partial(x, y)}{\partial(u, v)}$$

$$= \begin{vmatrix} \frac{1}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{vmatrix} = \frac{1}{4} - \left(-\frac{1}{4}\right) = \frac{1}{2}$$

$$\iint_D (x+y) dA = \iint_{D^*} u \cdot \frac{1}{2} du dv$$

$$= \int_0^4 \int_0^{\frac{1}{2}u} \frac{u}{2} dv du = \int_0^4 \frac{u^2}{4} du = \frac{4^3}{3 \cdot 4} = \frac{16}{3}$$

Idea of the proof



Since T is differentiable

$$T(u, v) = T(u_0, v_0) + dT(u_0, v_0) \begin{pmatrix} \Delta u \\ \Delta v \end{pmatrix} + \text{smaller error}$$

$$\begin{pmatrix} x_u(u_0, v_0) & x_v(u_0, v_0) \\ y_u(u_0, v_0) & y_v(u_0, v_0) \end{pmatrix}$$

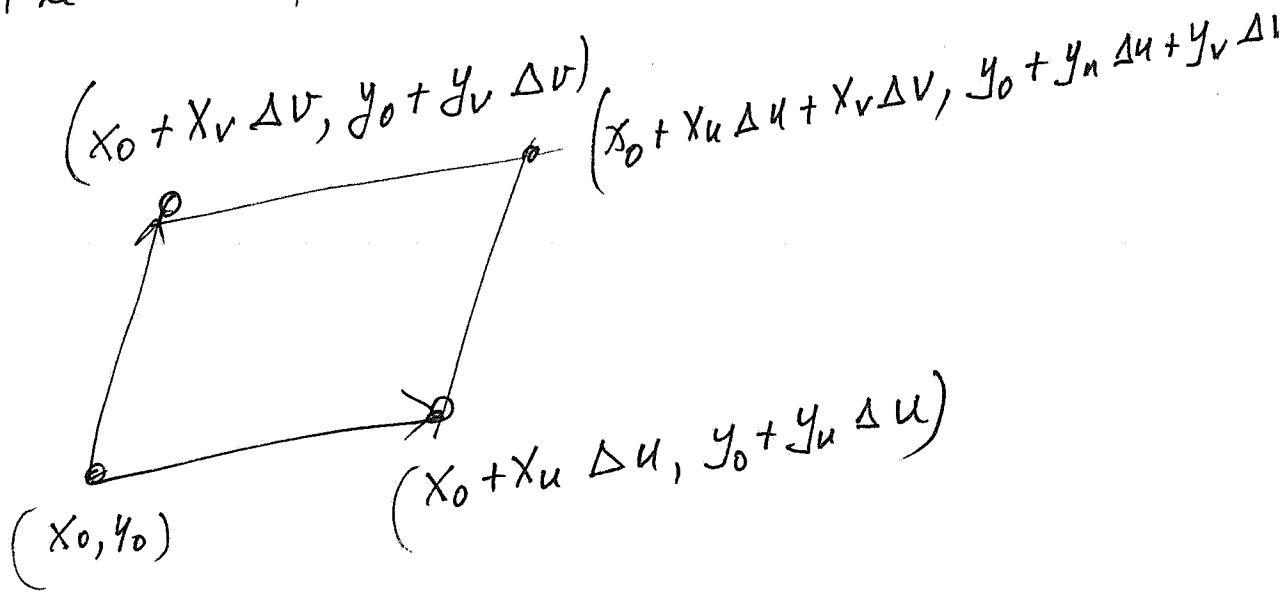
so the 4 corners of the small rectangle R are mapped to (approximately)

So

$$x(u, v) = x_0 + x_u(u_0, v_0)(u - u_0) + x_v(u_0, v_0)(v - v_0) + \text{smaller error}$$

$$y(u, v) = y_0 + y_u(u_0, v_0)(u - u_0) + y_v(u_0, v_0)(v - v_0) + \text{smaller error}$$

So the "4 corners" of the parallelogram in the x, y plane are



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so the area of the image $T(R)$

is (to first order)

$$\left| \begin{pmatrix} x_u(u_0, v_0) & y_u(u_0, v_0) \\ x_v(u_0, v_0) & y_v(u_0, v_0) \end{pmatrix} \Delta u \times \begin{pmatrix} x_v(u_0, v_0) & y_v(u_0, v_0) \end{pmatrix} \Delta v \right|$$

$$\approx \left| \frac{\partial(x, y)}{\partial(u, v)} \right| \Delta u \Delta v$$

(so $dx dy \approx \left| \frac{\partial(x, y)}{\partial(u, v)} \right| \Delta u \Delta v$)

Summing over rectangles in the Riemann sum makes the formula

$$\iint_D f(x, y) dx dy = \iint_{D^*} f(x(u, v), y(u, v)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv$$

plausible

Change of variables in triple integrals

(1)

The idea behind the change of variables theorem in three variables

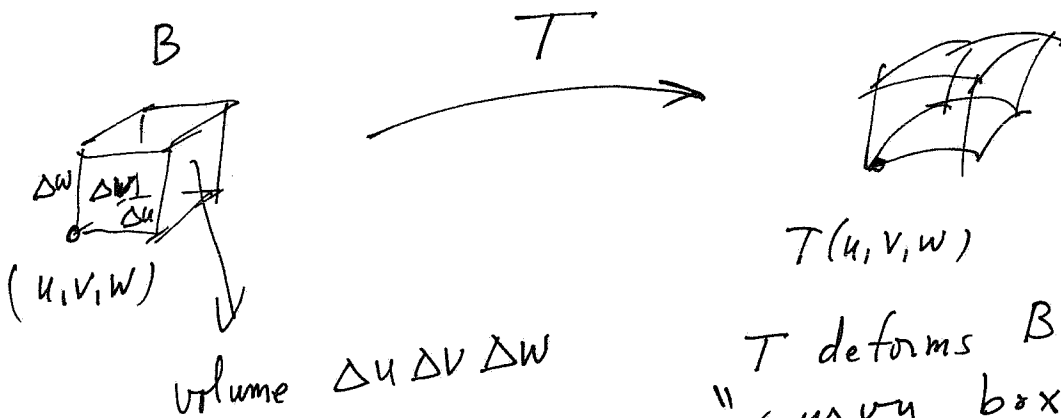
$$(u, v, w) \xrightarrow{T} (x, y, z)$$

is analogous to two variables

(only more complicated!)

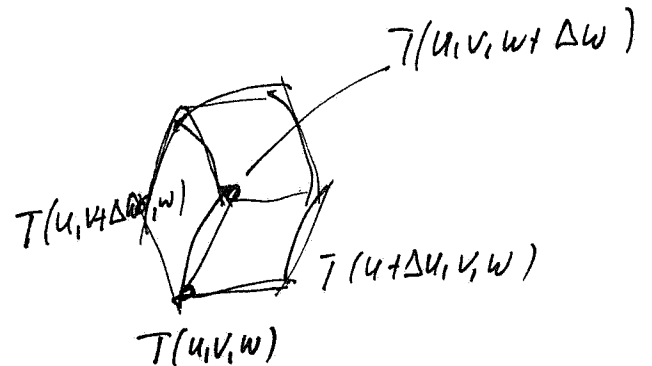
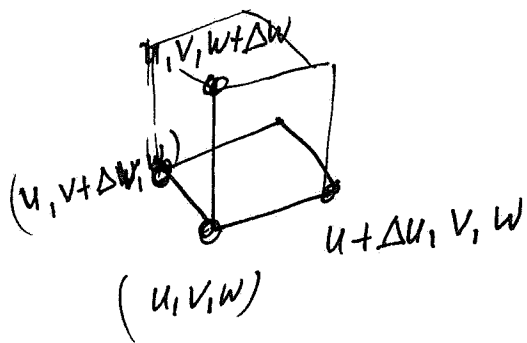
How does T change the volume

of an infinitesimal box B ?



2

Since T is differentiable, T is well approximated by its linear approximation (differential) so $T(B) \approx$ infinitesimal parallelepiped



The image $T(B)$ is generated by the three vectors

(3)

$$T(u+\Delta u, v, w) - T(u, v, w) \approx T_u(u, v, w) \Delta u$$

$$T(u, v+\Delta v, w) - T(u, v, w) \approx T_v(u, v, w) \Delta v$$

$$T(u, v, w+\Delta w) - T(u, v, w) \approx T_w(u, v, w) \Delta w$$

The volume of the curvy $T(B)$ is approximately given by the scalar triple product

$$\Delta V \approx \left| (T_u \Delta u \times T_v \Delta v) \cdot T_w \Delta w \right|$$

$$\approx \left| (T_u \times T_v) \cdot T_w \right| \Delta u \Delta v \Delta w$$

$$\approx \left| \det DT(u, v, w) \right| \Delta u \Delta v \Delta w$$

the Jacobian matrix

of the map T

Notation Write $T(u, v, w)$
 $= (x(u, v, w), y(u, v, w), z(u, v, w))$

Then we write

$$\det JT(u, v, w) = \frac{\partial(x, y, z)}{\partial(u, v, w)} = \det \begin{pmatrix} x_u & x_v & x_w \\ y_u & y_v & y_w \\ z_u & z_v & z_w \end{pmatrix}$$

So the terms of the Riemann sum

for the triple integral $\iiint_W f(x, y, z) dV$

have the form

$$f(T(u, v, w)) \left| \frac{\partial(x, y, z)}{\partial(u, v, w)} \right| \Delta u \Delta v \Delta w$$

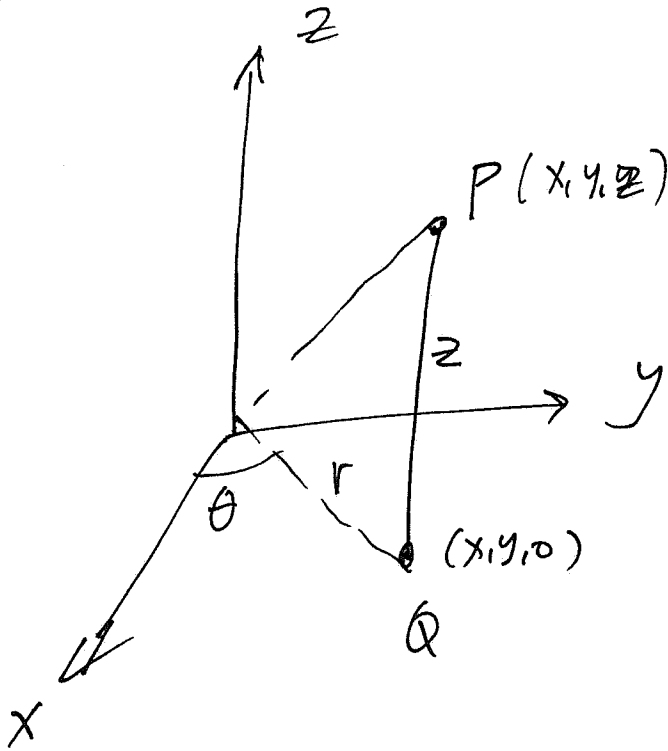
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In the limit as $\Delta u, \Delta v, \Delta w \rightarrow 0$:

$$\iiint_W f(x, y, z) dV = \iiint_{W^*} f(T(u, v, w)) \left| \frac{\partial(x, y, z)}{\partial(u, v, w)} \right| du dv dw$$

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cylindrical coordinates



use polar coordinates
for Q

$$\begin{aligned}x &= r \cos \theta \\y &= r \sin \theta \\z &= z\end{aligned}$$

Then

$$\frac{\partial(x, y, z)}{\partial(r, \theta, z)} = \begin{vmatrix} \cos \theta & -r \sin \theta & 0 \\ \sin \theta & r \cos \theta & 0 \\ 0 & 0 & 1 \end{vmatrix} = r$$

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Example 1. Let W be the region bounded above by $z = 16 - x^2 - y^2$ and below by the x, y plane.

Evaluate $\iiint_W (8 + x + y) dV =$

Introduce cylindrical coordinates

$x = r \cos \theta$
 $y = r \sin \theta$
 $z = z$

$0 \leq z \leq 16 - r^2$
 $0 \leq r \leq 4$
 $0 \leq \theta \leq 2\pi$

} W^*

$= \int_0^{2\pi} \int_0^4 \int_0^{16-r^2} (8 + r \cos \theta + r \sin \theta) r dz dr d\theta$

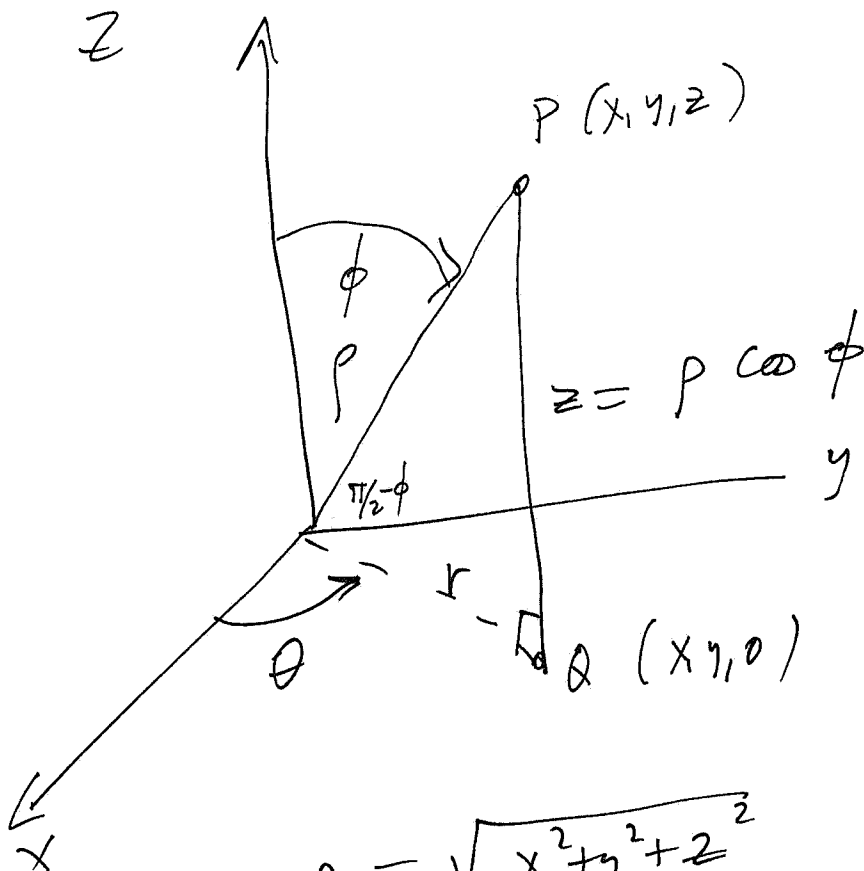
$= \int_0^4 \int_0^{2\pi} \int_0^{16-r^2} (8 + r \cos \theta + r \sin \theta) r dz d\theta dr$

$= \int_0^4 \int_0^{2\pi} r(16-r^2)(8 + r \cos \theta + r \sin \theta) d\theta dr$

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$$= \int_0^4 r(16-r^2) \cdot 16\pi \, dr = 1024\pi$$

Spherical coordinates



$$\rho = \sqrt{x^2 + y^2 + z^2}$$

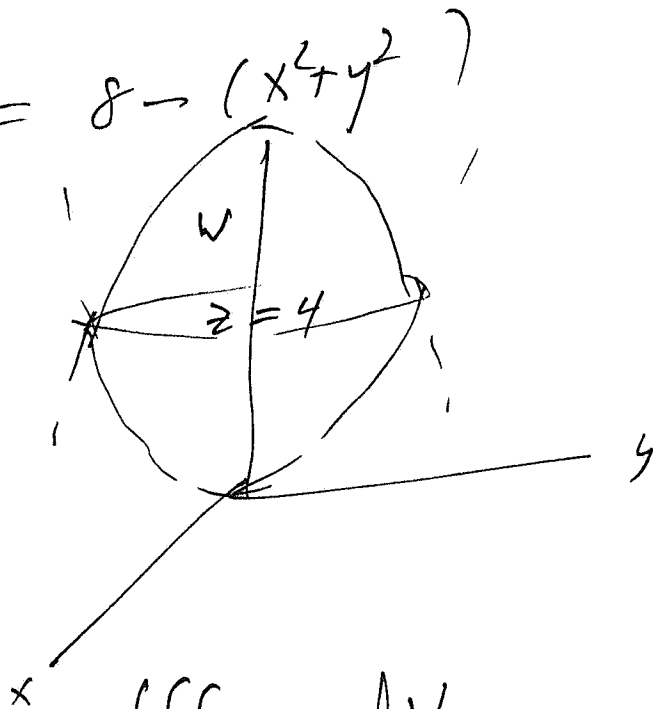
$$x = \rho \sin \phi \cos \theta$$

$$y = \rho \sin \phi \sin \theta$$

$$r = \sqrt{x^2 + y^2} \\ = \rho \sin \phi$$

(8.1)

Example Let w be the region enclosed by the paraboloids $z = x^2 + y^2$ and $z = 8 - (x^2 + y^2)$



Evaluate $\iiint_W xyz \, dV$

$$= \int_0^{2\pi} \int_0^2 \int_{r^2}^{8-r^2} (r \cos \theta)(r \sin \theta) z \cdot r \, dz \, r \, d\theta$$

$$= \int_0^{2\pi} \int_0^2 \left(\frac{(8-r^2)^2 - r^4}{2} \right) \cdot r^3 \, dr \, d\theta$$

$$= \pi \int_0^2 (64 - 16r^2) r^3 \, dr$$

(skip calculation, just state)

$$\frac{\partial(x, y, z)}{\partial(\rho, \theta, \phi)} = \begin{vmatrix} \sin\phi \cos\theta & -\rho \sin\phi \sin\theta & \rho \cos\phi \cos\theta \\ \sin\phi \sin\theta & \rho \sin\phi \cos\theta & \rho \cos\phi \sin\theta \\ \cos\phi & 0 & -\rho \sin\phi \end{vmatrix}$$

Expand by cofactors along last row:

$$\frac{\partial(x, y, z)}{\partial(\rho, \theta, \phi)} = \cos\phi \begin{vmatrix} -\rho \sin\phi \sin\theta & \rho \cos\phi \cos\theta \\ \rho \sin\phi \cos\theta & \rho \cos\phi \sin\theta \end{vmatrix} - \rho \sin\phi \begin{vmatrix} \sin\phi \cos\theta & -\rho \sin\phi \sin\theta \\ \sin\phi \sin\theta & \rho \sin\phi \cos\theta \end{vmatrix}$$

$$= \cos\phi \cdot -\rho^2 \sin\phi \cos\phi - \rho \sin\phi \cdot \rho \sin^2\phi$$

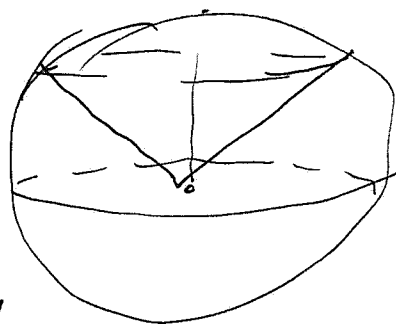
$$= -\rho^2 \sin\phi$$

$$\iiint_W f(x, y, z) dx dy dz = \iiint_{W^*} f(\rho \sin\phi \cos\theta, \rho \sin\phi \sin\theta, \rho \cos\phi) \rho^2 \sin\phi d\rho d\theta d\phi$$

Example 1 Find the volume of

the ice cream cone region bounded above by the upper hemisphere

$z = \sqrt{1-x^2-y^2}$ and below by the cone $z = x^2+y^2$



on the cone $z = \sqrt{x^2+y^2}$, $\phi = \pi/4$

W^* : $0 \leq \theta \leq 2\pi$, $0 \leq \rho \leq 1$, $0 \leq \phi \leq \pi/4$

$$\text{Vol } W = \int_0^1 \int_0^{2\pi} \int_0^{\pi/4} \rho^2 \sin \phi \, d\phi \, d\theta \, d\rho$$

$$= \frac{2\pi}{3} \int_0^{\pi/4} \sin \phi \, d\phi = \frac{2\pi}{3} \left(1 - \frac{\sqrt{2}}{2}\right)$$

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Example 2 The density of an object occupying the upper hemisphere $x^2 + y^2 + z^2 \leq 1$ is $\rho(x, y, z) = z$. Find the total mass.

Solution

We use spherical coordinates to

evaluate $M = \iiint_W z \, dV$

$$= \int_0^{\pi/2} \int_0^{2\pi} \int_0^1 \rho \cos \phi \, \rho^2 \sin \phi \, d\rho \, d\theta \, d\phi$$

$$= \frac{1}{4} \cdot 2\pi \int_0^{\pi/2} \sin \phi \, d(\sin \phi) = \frac{\pi}{4}$$

Remark

Do not forget you can use linear change of variable in Triple integrals.

Example Find the volume of the

parallel piped

$$\begin{aligned}
 0 &\leq 2x - 3y + z \leq 5 \\
 1 &\leq x + 2y \leq 4 \\
 -3 &\leq x - z \leq 6
 \end{aligned}$$

Introduce new variables

$$\begin{array}{l|l}
 u = 2x - 3y + z & 0 \leq u \leq 5 \\
 v = x + 2y & 1 \leq v \leq 4 \\
 w = x - z & -3 \leq w \leq 6
 \end{array}$$

W^*

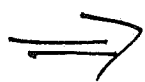
Then $\frac{\partial(u, v, w)}{\partial(x, y, z)} = \begin{vmatrix} 2 & -3 & 1 \\ 1 & 2 & 0 \\ 1 & 0 & -1 \end{vmatrix}$

cofactors along
3rd row

$$= 1 \cdot \begin{vmatrix} -3 & 1 \\ 2 & 0 \end{vmatrix} - 1 \cdot \begin{vmatrix} 2 & -3 \\ 1 & 2 \end{vmatrix}$$

$$= -2 - 7 = -9$$

Jacobian of inverse



$$\left| \frac{\partial(x, y, z)}{\partial(u, v, w)} \right| = \frac{1}{9}$$

$$\text{Vol} = \iiint_{W^*} \frac{1}{9} du dv dw$$

$$= \frac{1}{9} \cdot 5 \cdot 3 \cdot 9 = 15$$